

Diarization of overlapping speech:

Methods and ensembles

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Overview

- A brief **background in diarization**:
 - The task and its applications
 - A traditional solution, and the problem of overlapping speech
- **Methods**:
 - Overlap-aware clustering
 - Separate then diarize
- **Ensemble**: An approach for combining overlap-aware diarization systems

Background

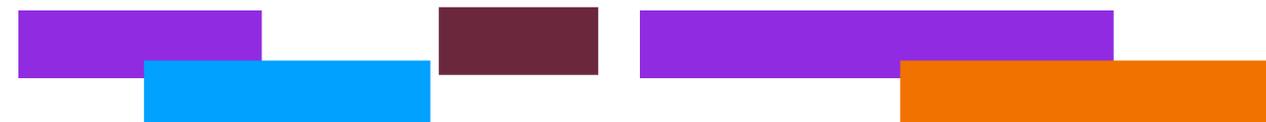
What is speaker diarization?

Task of “who spoke when”

Input: *recording containing multiple speakers*



Output: *homogeneous speaker segments*



Background

Applications of Diarization



Psychotherapy and human interaction



Child language acquisition



Collaborative learning



Meeting transcription



Cocktail party problem

Background

What makes Diarization difficult?



Input: *recording containing multiple speakers*



Output: *homogeneous speaker segments*

1. The recording may be very long with arbitrary silences/noise.
2. Number of speakers may be unknown.
3. Overlapping speech may be present.

**Example from CHiME-6 challenge
(best system achieved >30% error rate)**

The traditional solution

“Clustering-based” systems

- **Key idea:** formulate Diarization as a clustering problem
- Cluster small segments of audio
- Each cluster represents a distinct speaker

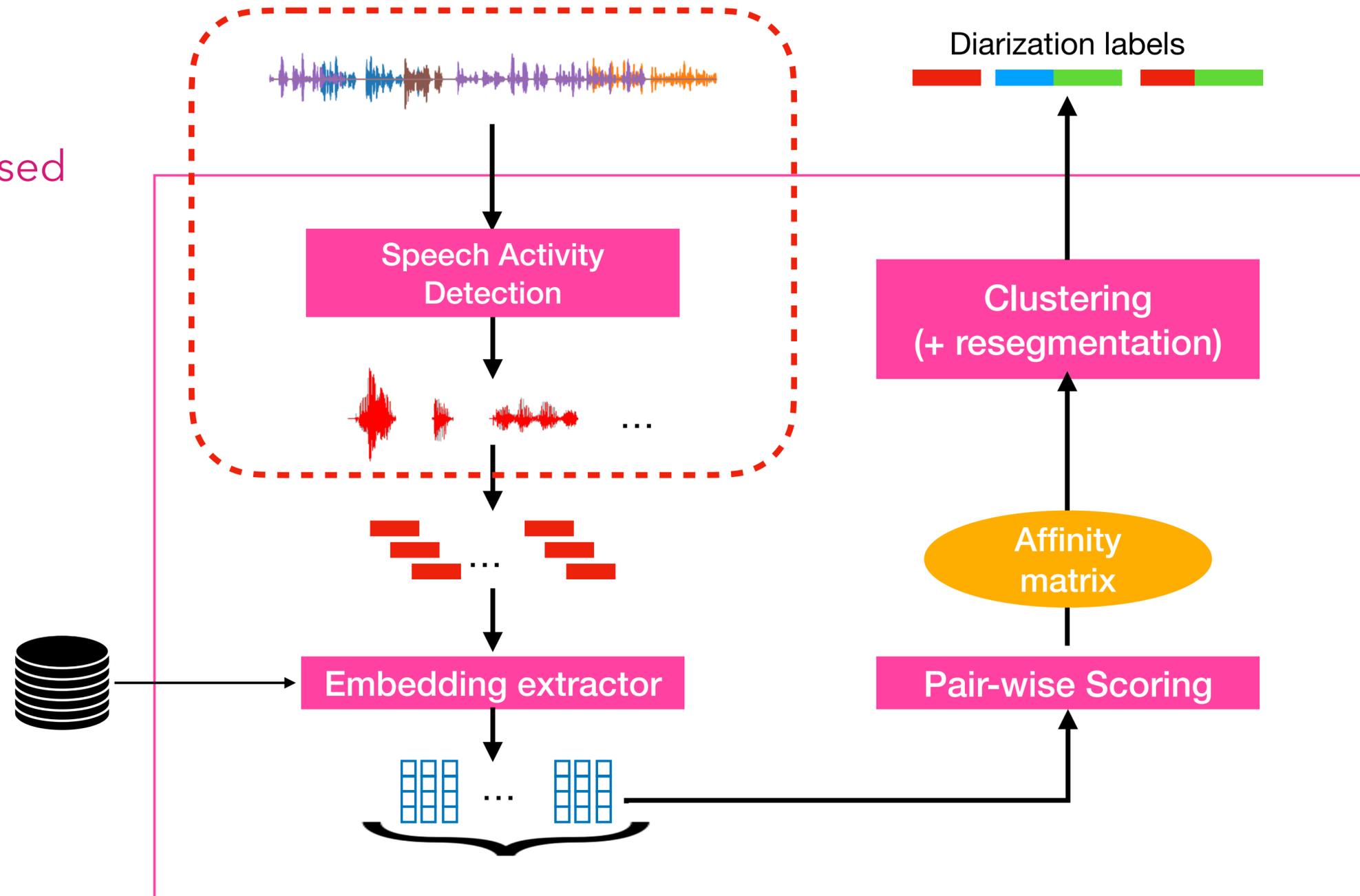
Basu, J., Khan, S., Roy, R., Pal, M., Basu, T., Bepari, M.S., & Basu, T.K. (2016). An overview of speaker diarization: Approaches, resources and challenges.

Tranter, S., & Reynolds, D. (2006). An overview of automatic speaker diarization systems. IEEE Transactions on Audio, Speech, and Language Processing.

Clustering-based diarization

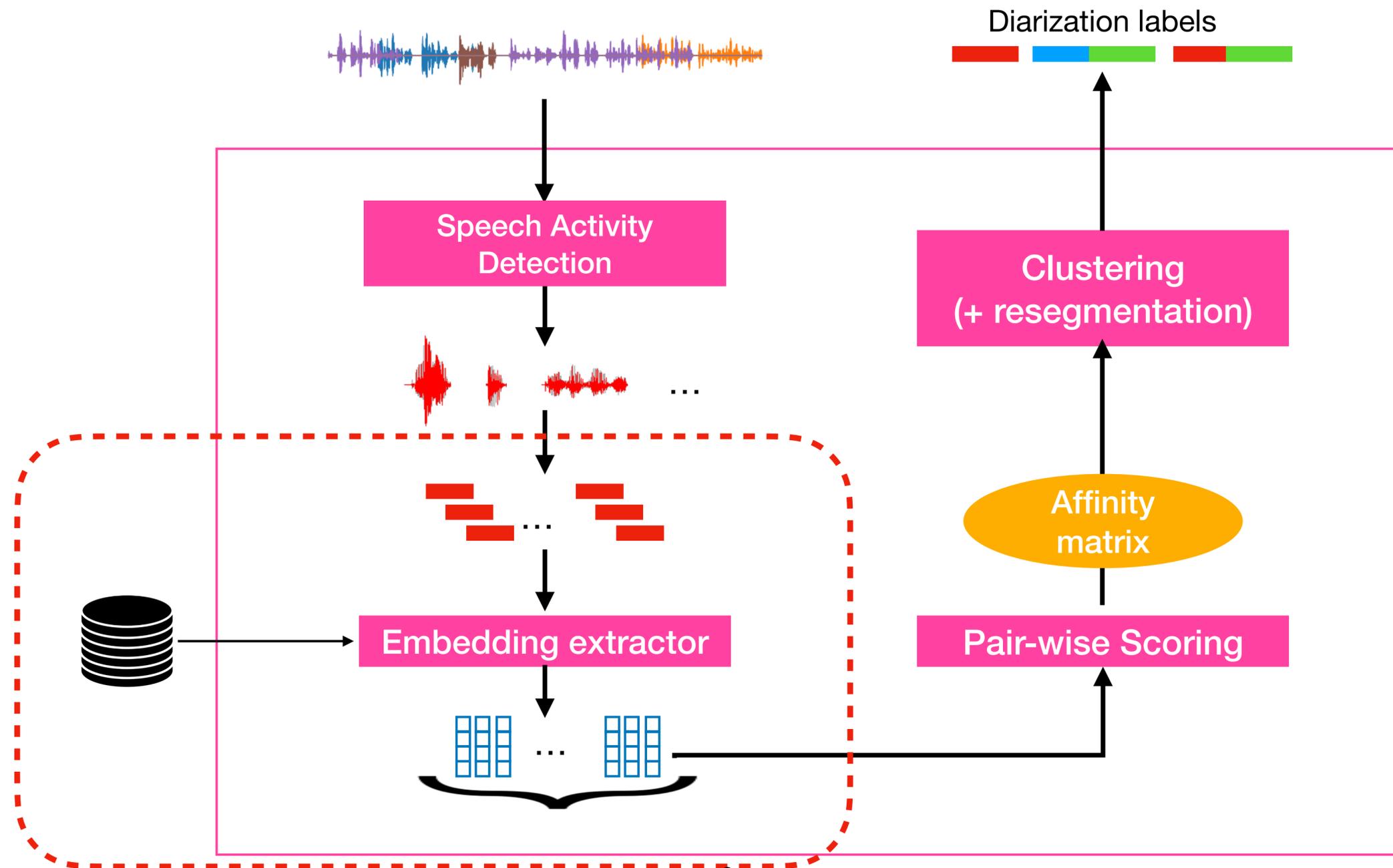
SAD extracts speech segments from recordings

Spectral energy-based
GMM-based
Hybrid HMM-DNN
End-to-end SAD



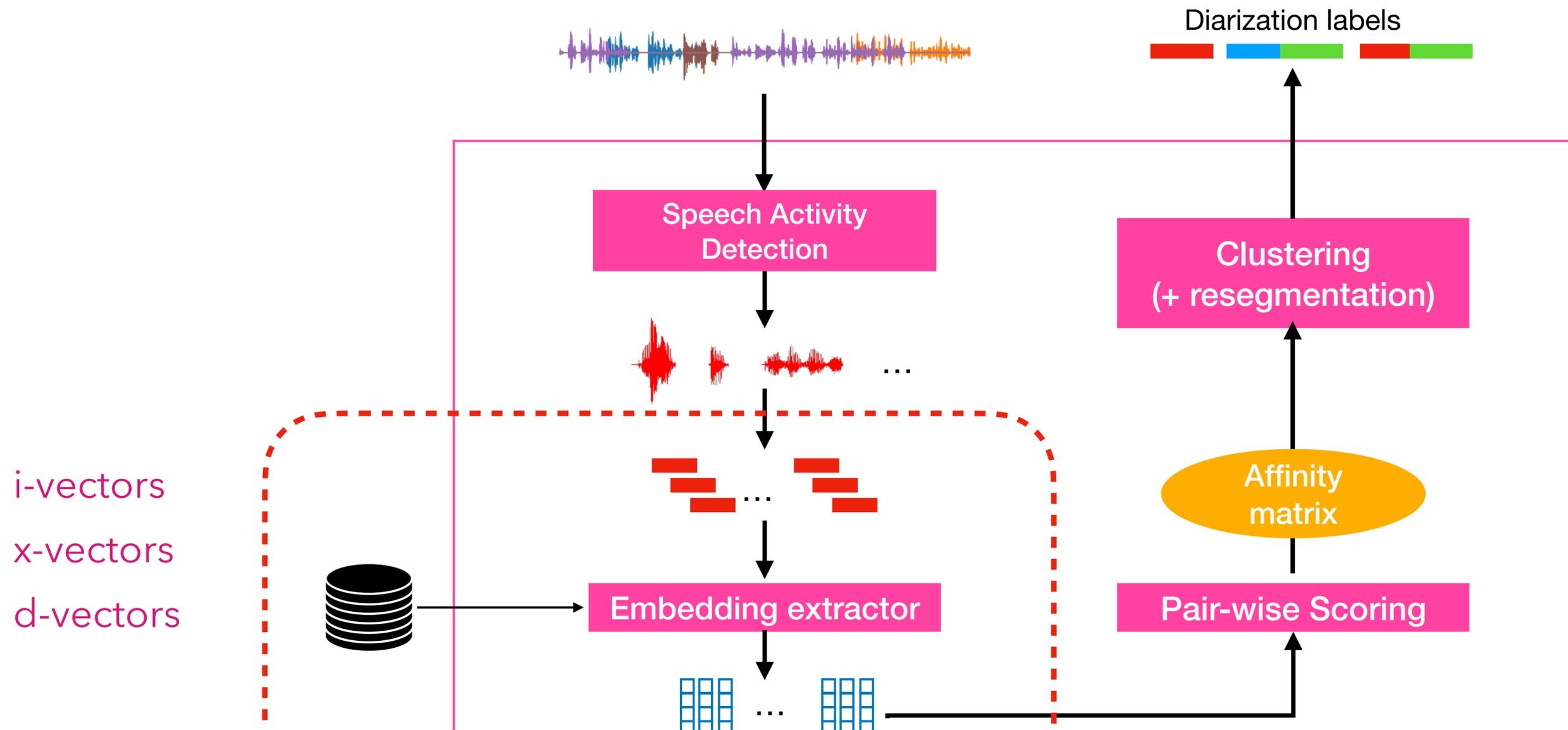
Clustering-based diarization

Embeddings extracted for small subsegments



Clustering-based diarization

Embeddings extracted for small subsegments



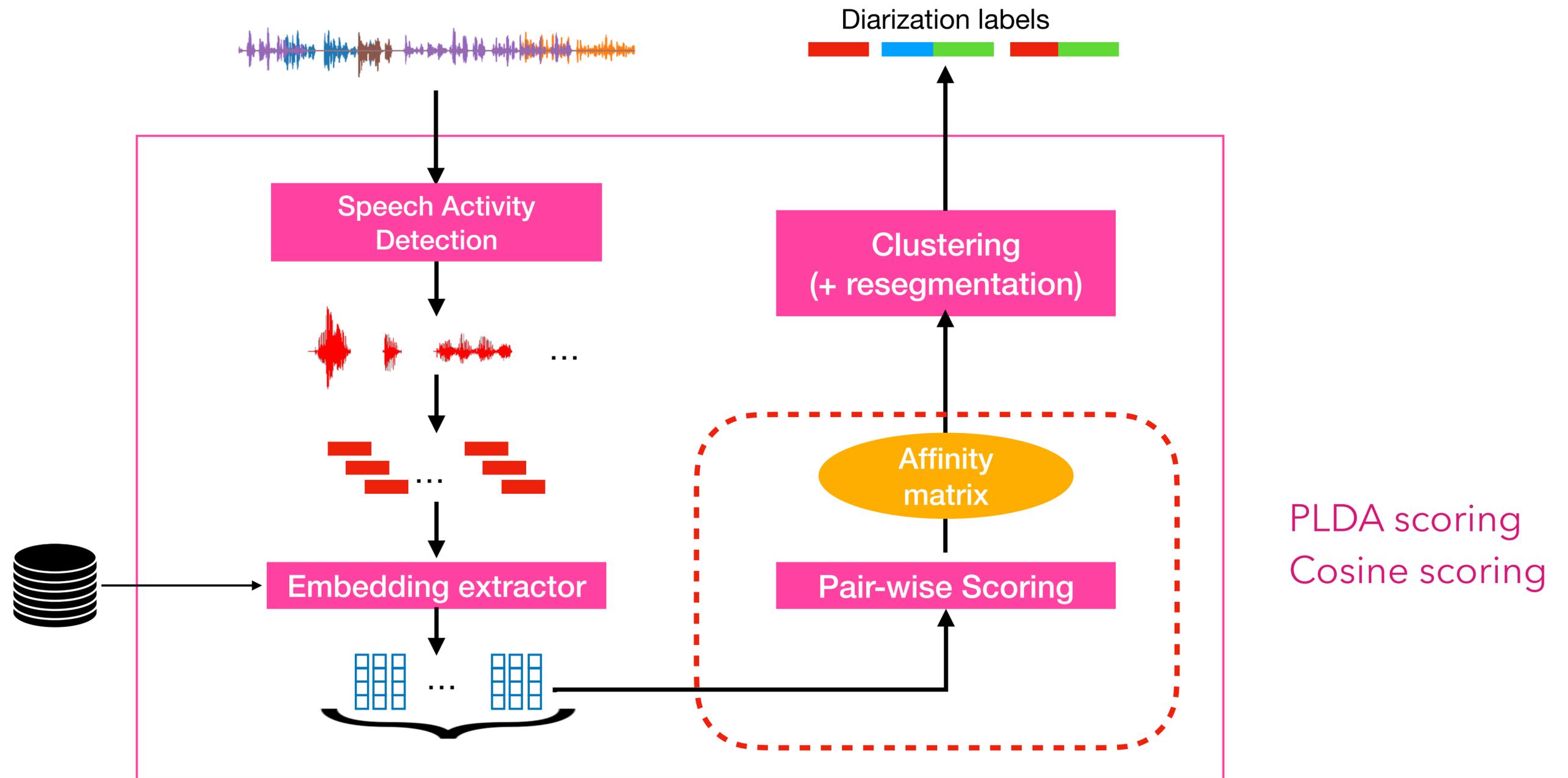
Dehak, N., et al (2011). Front-End Factor Analysis for Speaker Verification. *IEEE Transactions on Audio, Speech, and Language Processing*.

Snyder, D., et al. (2018). X-Vectors: Robust DNN Embeddings for Speaker Recognition. *2018 IEEE ICASSP*.

Varianni, E., et al. (2014). Deep neural networks for small footprint text-dependent speaker verification. *2014 IEEE ICASSP*.

Clustering-based diarization

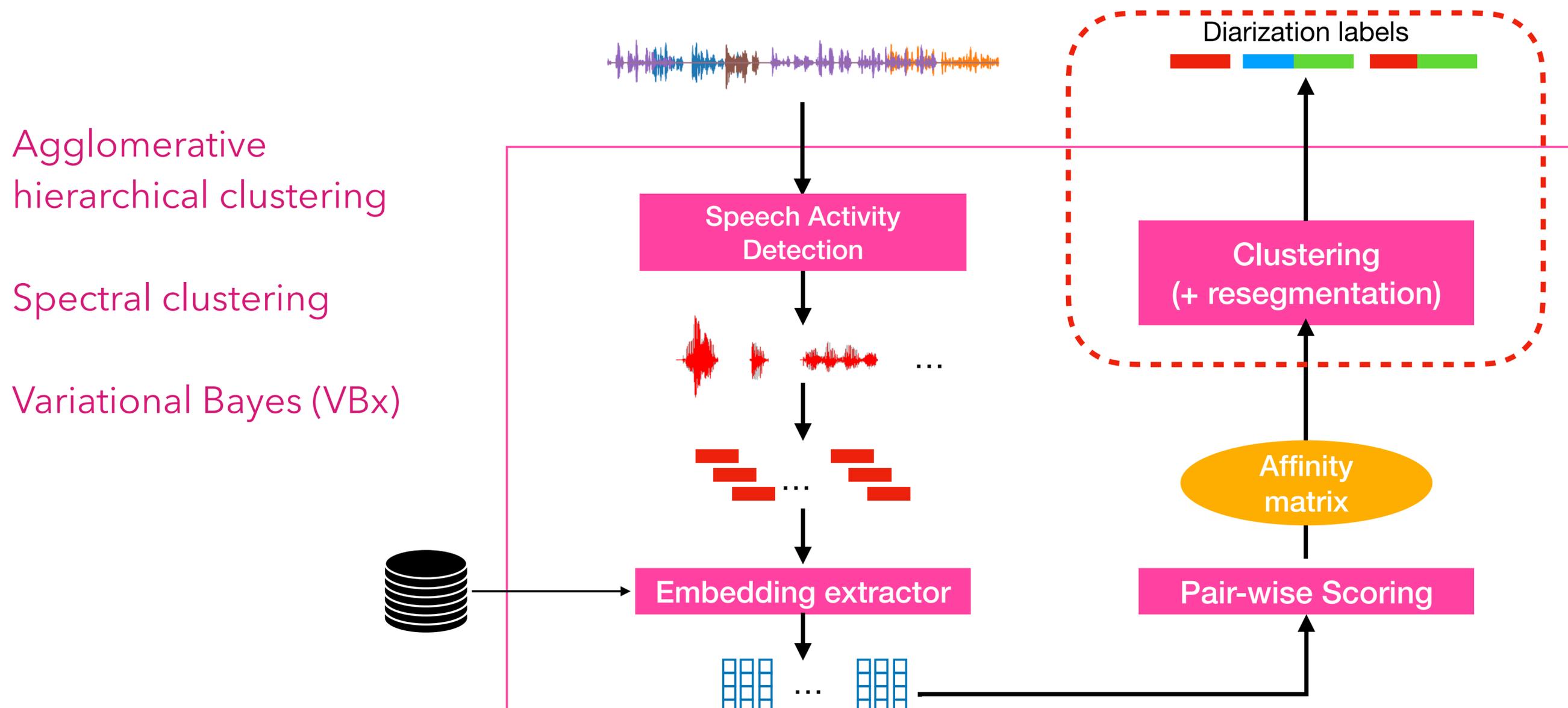
Pair-wise scoring of subsegments



Sell, G., & Garcia-Romero, D. (2014). Speaker diarization with PLDA i-vector scoring and unsupervised calibration. *2014 IEEE Spoken Language Technology Workshop (SLT)*.

Clustering-based diarization

Clustering based on the affinity matrix, followed by optional resegmentation



Daniel Garcia-Romero, David Snyder, Gregory Sell, Daniel Povey, and Alan McCree, "Speaker diarization using deep neural network embeddings," ICASSP 2017.
Mireia Díez, Lukas Burget, and Pavel Matejka, "Speaker diarization based on Bayesian HMM with eigenvoice priors," Odyssey 2018.

Clustering-based diarization

How well does it perform?

- **Winning system in DIHARD I (2018) and II (2019)**
- DIHARD contains “hard” Diarization evaluation with recordings from several domains
- But **Diarization error rates (DER) still high**: 37% in DIHARD I and 27% in DIHARD II

$$\text{DER} = \frac{\text{Missed speech} + \text{False alarm} + \text{Speaker error}}{\text{Total speaking time}}$$

Sell, G., et al. (2018). Diarization is Hard: Some Experiences and Lessons Learned for the JHU Team in the Inaugural DIHARD Challenge. *INTERSPEECH 2018*.

Landini, F., et al. (2020). BUT System for the Second Dihad Speech Diarization Challenge. *IEEE ICASSP 2020*.

Clustering paradigm assumes single-speaker segments

So overlapping speakers are completely ignored!

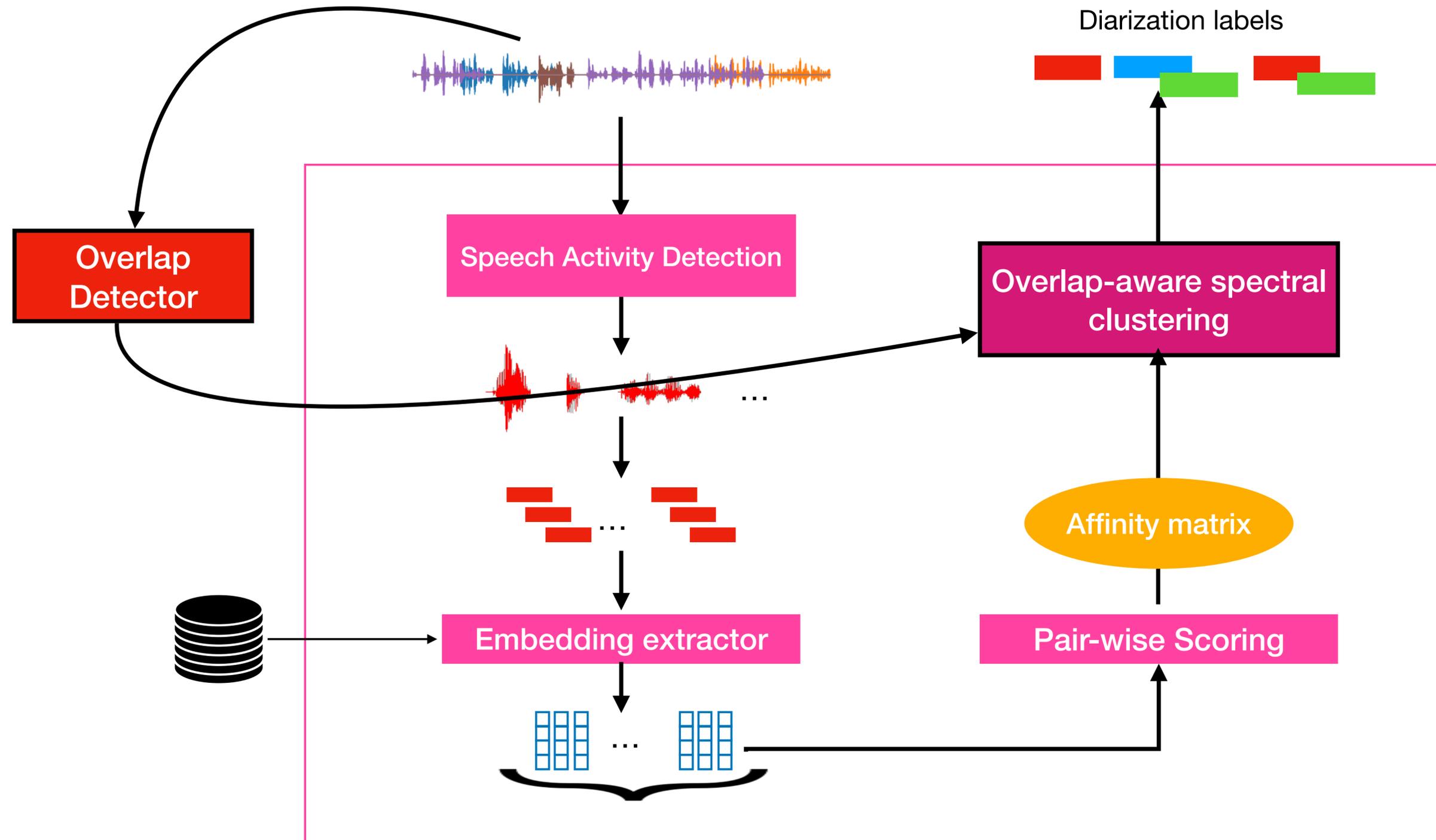
*"Roughly 8% of the absolute error in our systems was from overlapping speech ... it will likely require a **complete rethinking of the diarization process** ... This is an important direction, but could not be addressed ..."*

- JHU team (2018)

*"Given the current performance of the systems, the **overlapped speech gains more relevance** ... **more than 50% of the DER** in our best systems ... has to be addressed in the future ..."*

- BUT team (2019)

Overlap-aware spectral clustering



Raj, D., Huang, Z., & Khudanpur, S. (2021). Multi-class Spectral Clustering with Overlaps for Speaker Diarization. *IEEE SLT 2021*.

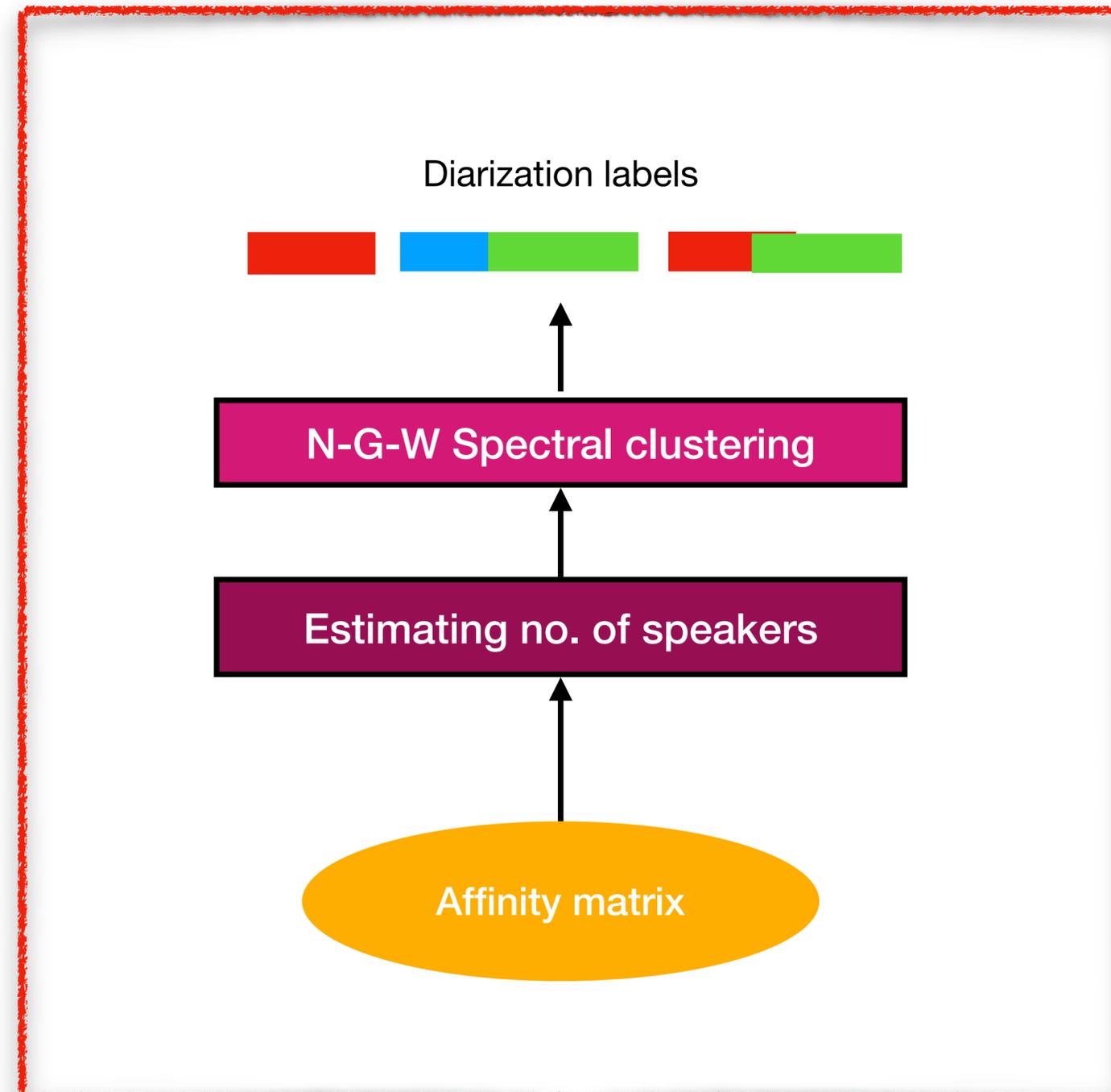
Overlap-aware spectral clustering

Overview of differences

Regular spectral clustering

(Ng-Jordan-Weiss algorithm):

- Estimate number of speakers (say, K)
- Compute Laplacian L of affinity matrix
- Apply K-means clustering on first K eigenvectors of L



Andrew Y. Ng, Michael I. Jordan, and Yair Weiss, "On spectral clustering: Analysis and an algorithm," NIPS, 2001

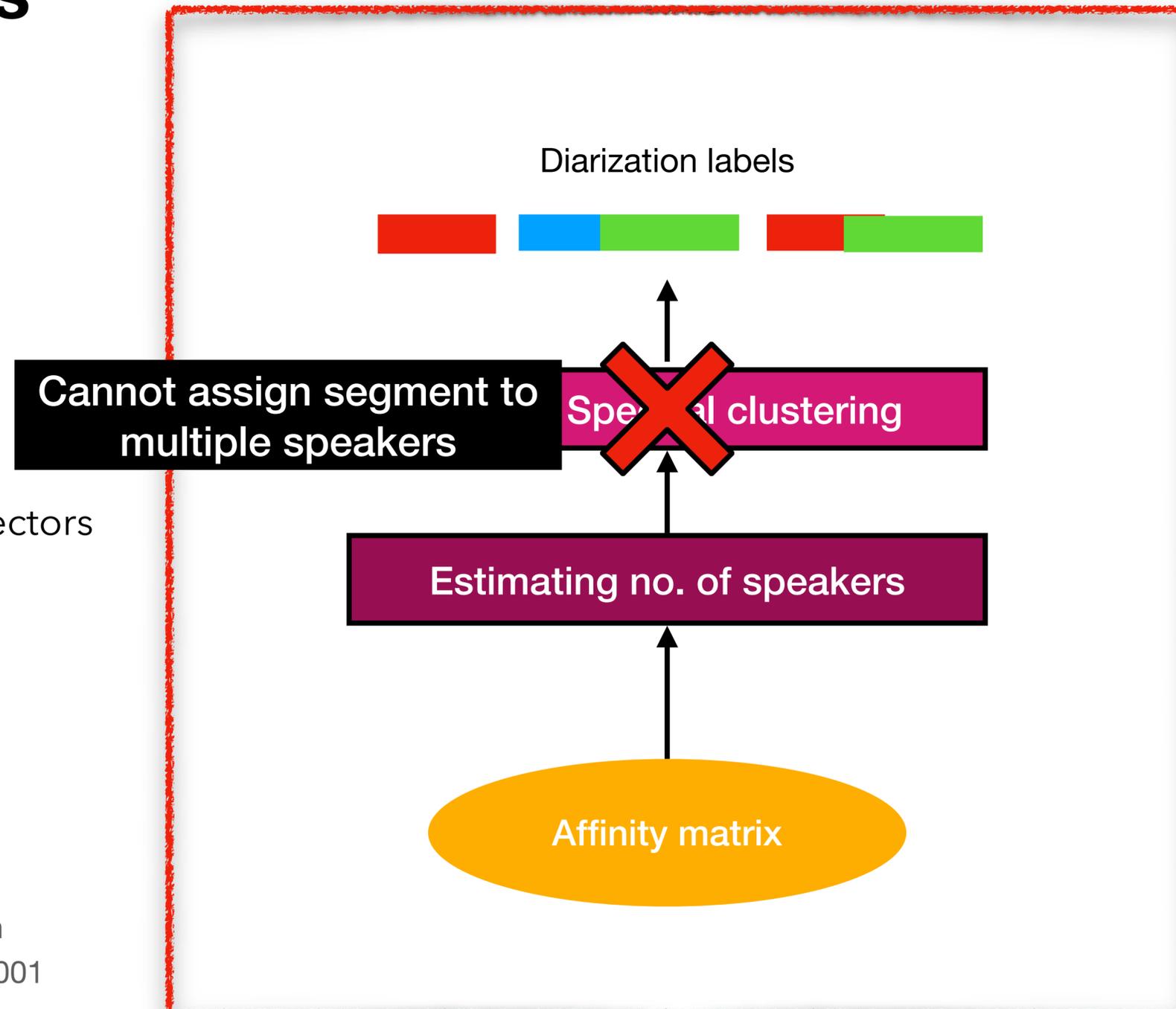
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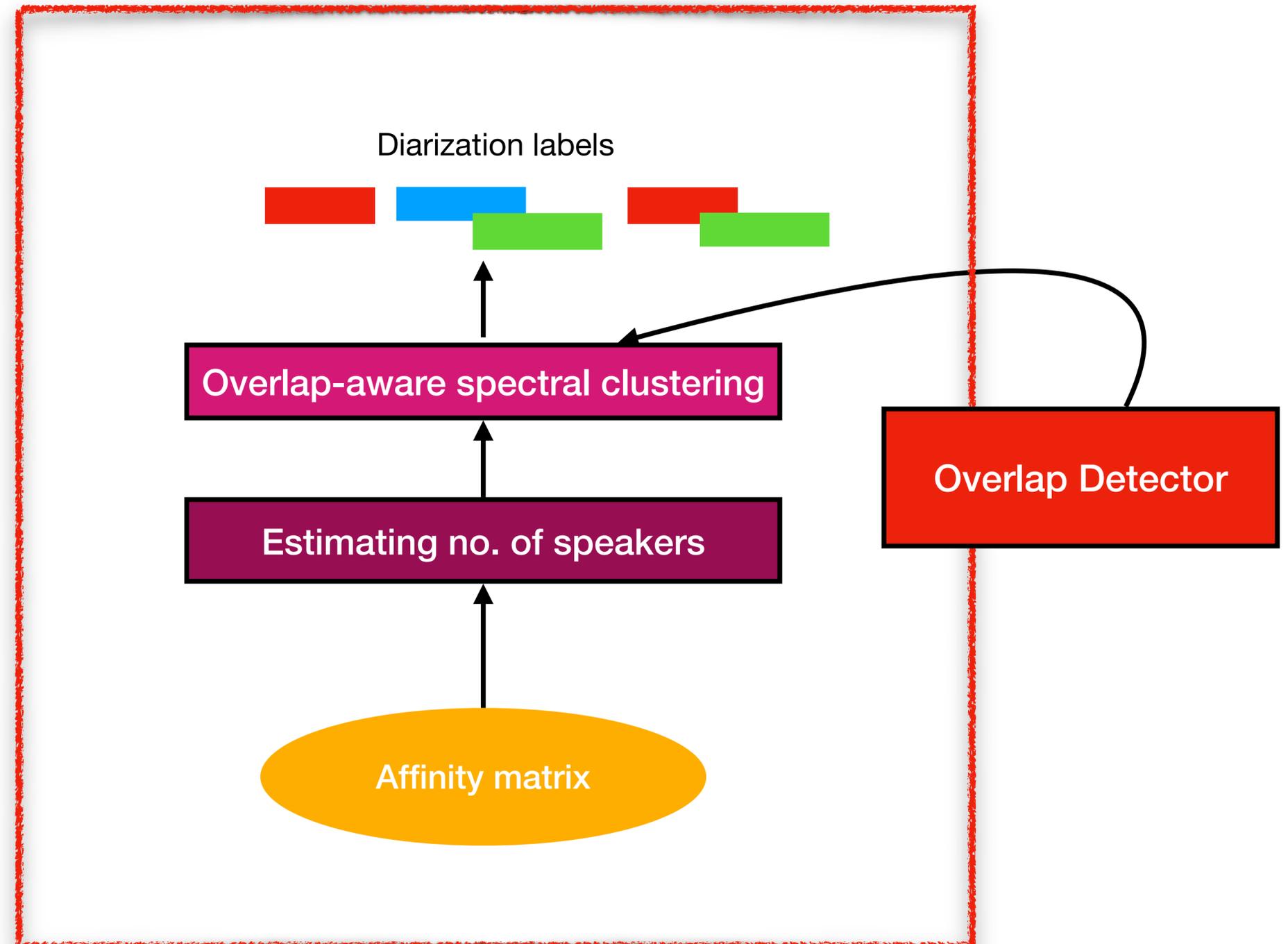


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Overlap-aware spectral clustering

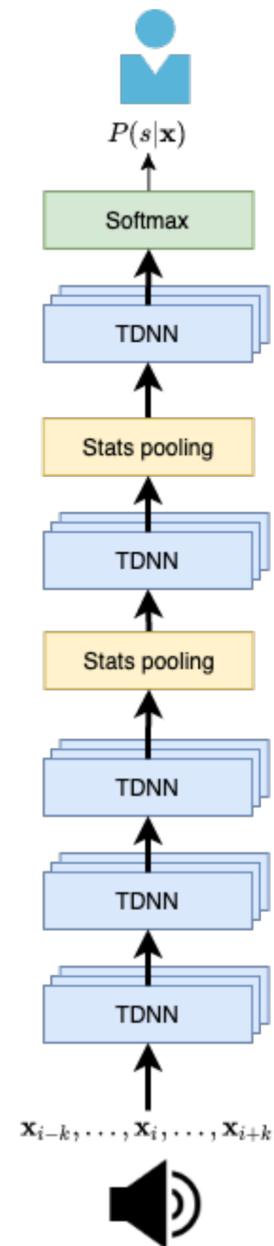
Overview of differences

**Alternative formulation:
multi-class spectral clustering**

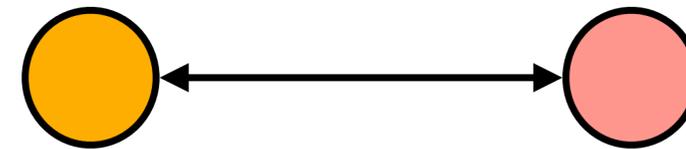
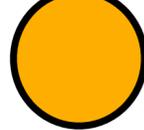


New formulation for spectral clustering

The basic clustering problem: a graph view



x-vector

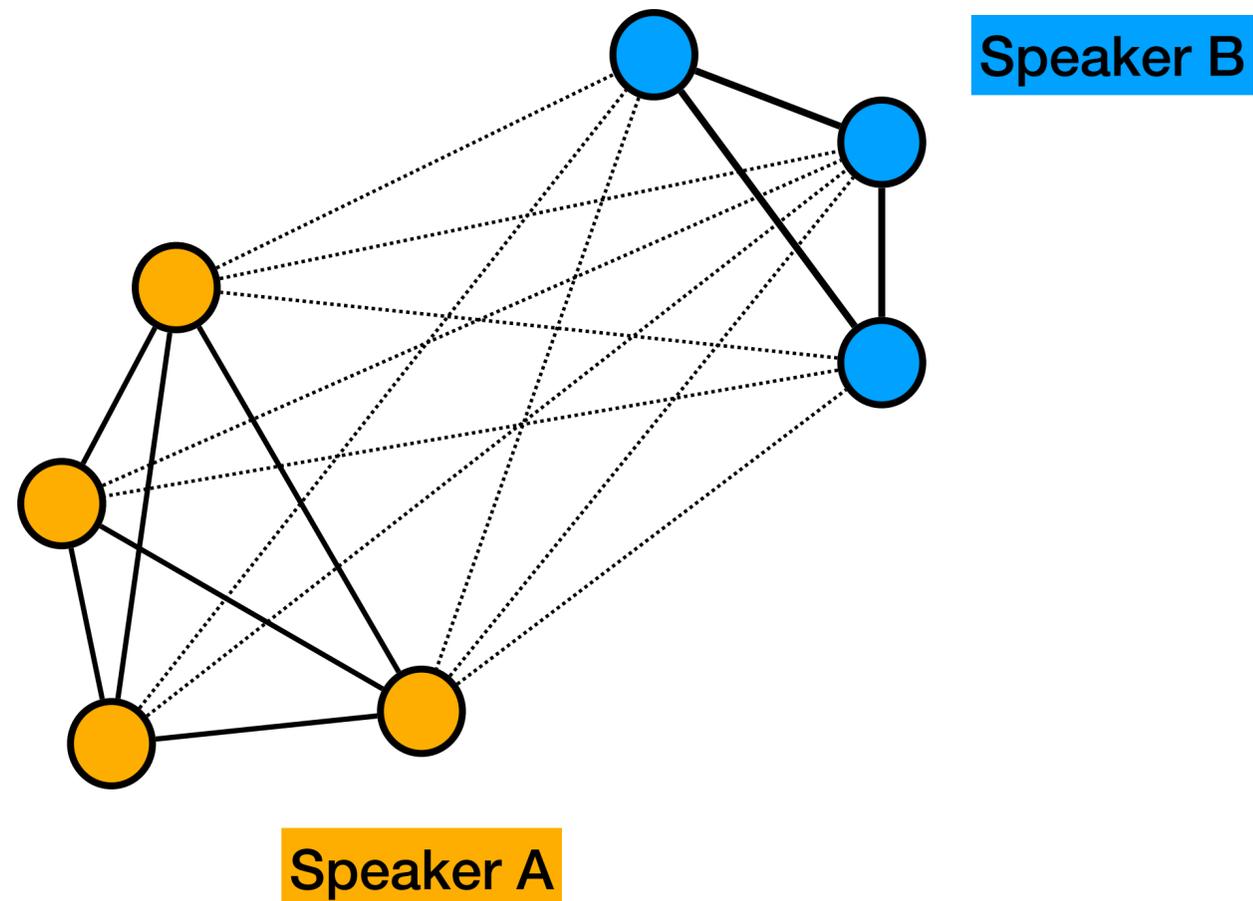


Cosine similarity

Snyder, D., et al. (2018). X-Vectors: Robust DNN Embeddings for Speaker Recognition. *2018 IEEE ICASSP*.

New formulation for spectral clustering

The basic clustering problem: a graph view



Edge weights within a group

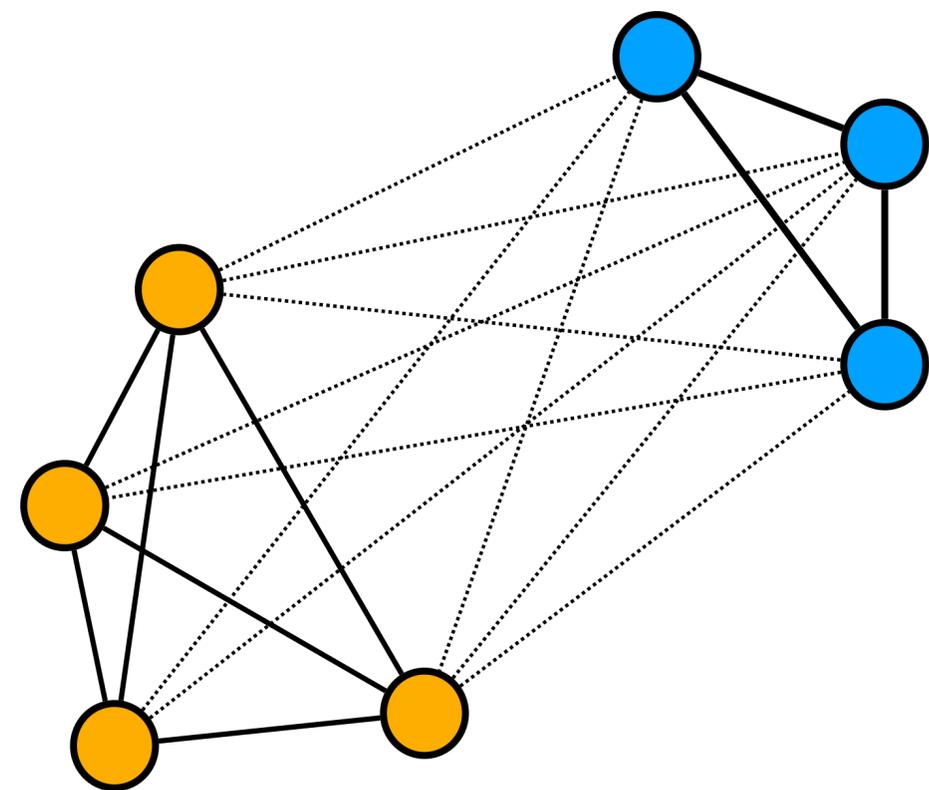


Edge weights across groups



New formulation for spectral clustering

The basic clustering problem: a graph view



Speaker B

Speaker A

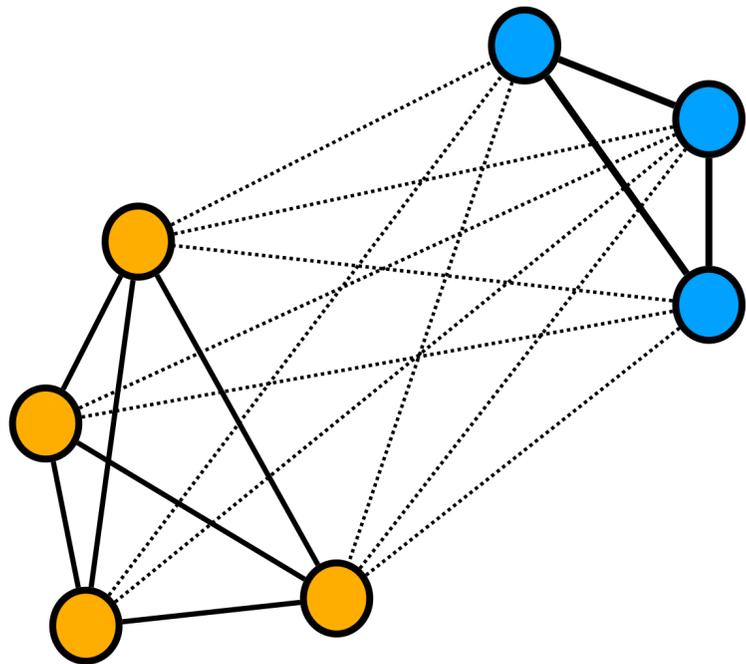
maximize

Edge weights within a group

Edge weights across groups

New formulation for spectral clustering

The basic clustering problem: a graph view



maximize

Edge weights within a group

Edge weights across groups

maximize

$$\epsilon(X) = \frac{1}{K} \sum_{k=1}^K \frac{X_k^T A X_k}{X_k^T D X_k}$$

subject to

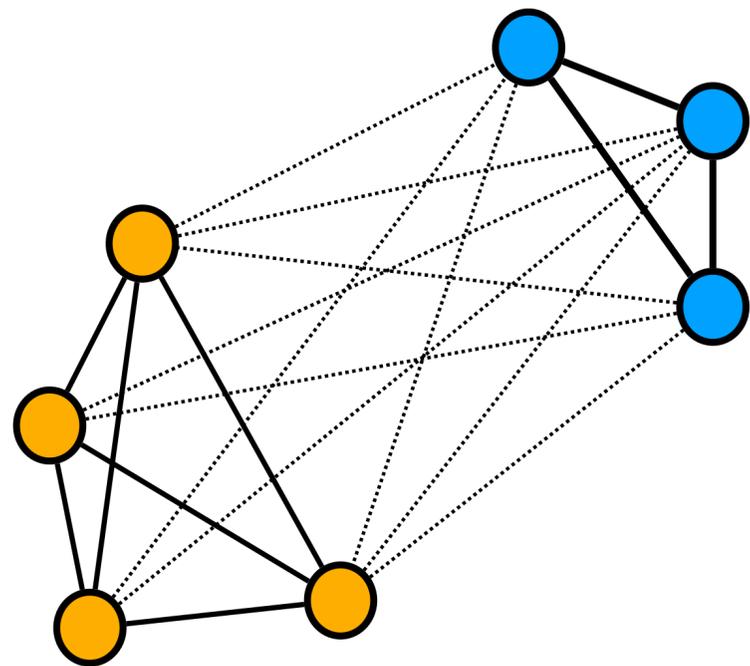
$$X \in \{0,1\}^{N \times K},$$

$$X \mathbf{1}_K = \mathbf{1}_N.$$

K speakers, **N** segments

New formulation for spectral clustering

The basic clustering problem: a graph view



maximize

Edge weights within a group

Edge weights across groups

maximize

$$\epsilon(X) = \frac{1}{K} \sum_{k=1}^K \frac{X_k^T \mathbf{A} X_k}{X_k^T \mathbf{D} X_k}$$

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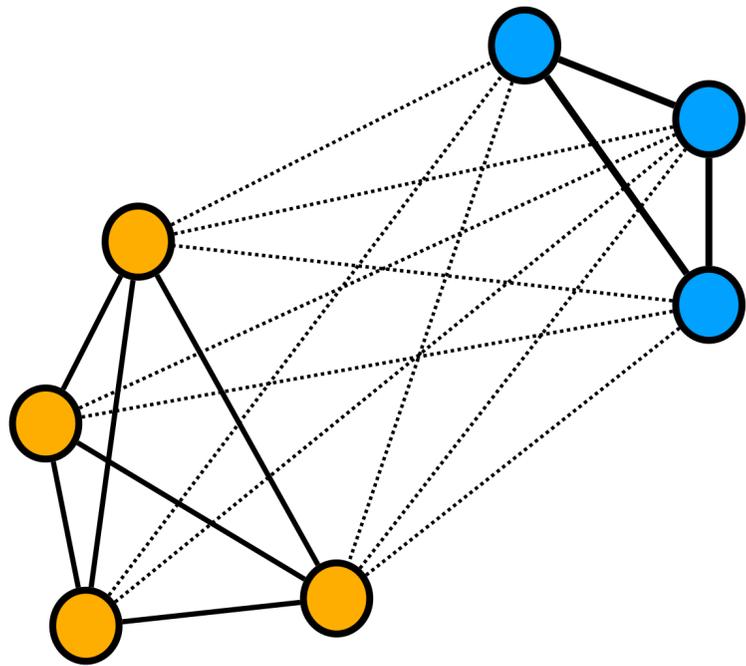
$$X \mathbf{1}_K = \mathbf{1}_N.$$

Affinity matrix

Diagonal matrix containing degree of nodes

New formulation for spectral clustering

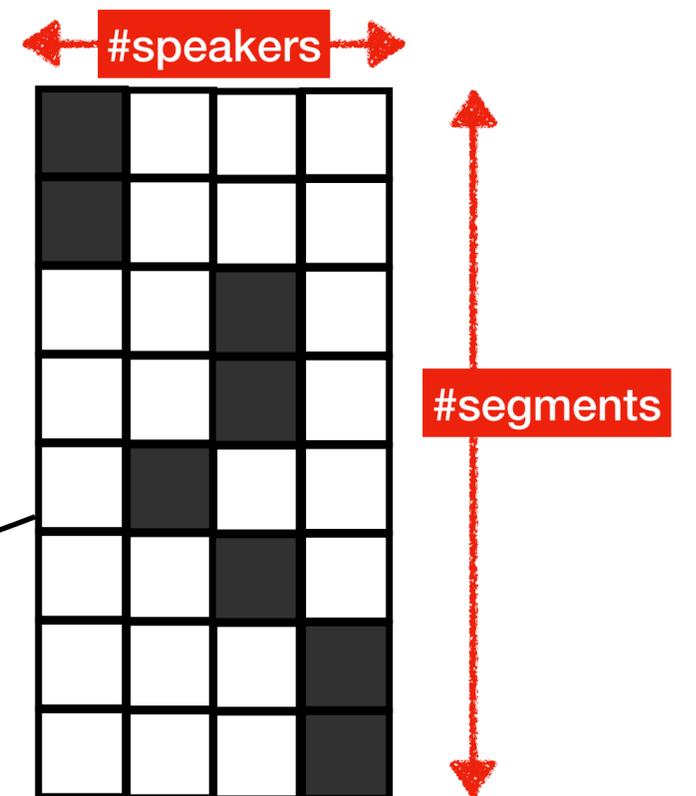
The basic clustering problem: a graph view



maximize $\epsilon(X) = \frac{1}{K} \sum_{k=1}^K \frac{X_k^T \mathbf{A} X_k}{X_k^T \mathbf{D} X_k}$

subject to $X \in \{0,1\}^{N \times K},$

$X \mathbf{1}_K = \mathbf{1}_N.$



Final cluster assignment matrix

New formulation for spectral clustering

This problem is NP-hard!

$$\begin{aligned} \text{maximize} \quad & \epsilon(X) = \frac{1}{K} \sum_{k=1}^K \frac{X_k^T \mathbf{A} X_k}{X_k^T \mathbf{D} X_k} \\ \text{subject to} \quad & X \in \{0, 1\}^{N \times K}, \\ & X \mathbf{1}_K = \mathbf{1}_N. \end{aligned}$$

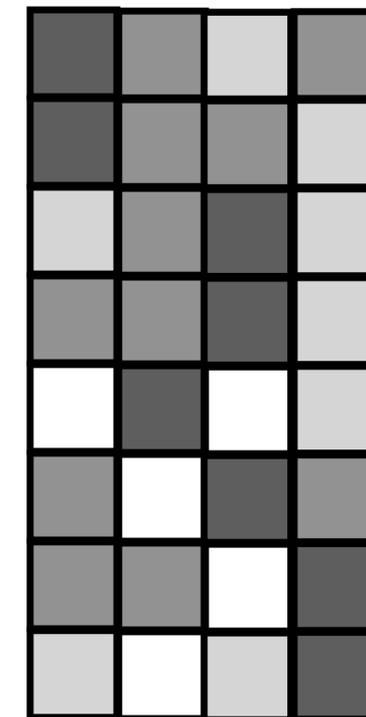
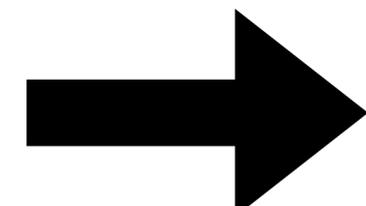
Remove the discrete constraints to make the problem solvable

New formulation for spectral clustering

Relaxed problem has a set of solutions

maximize $\epsilon(X) = \frac{1}{K} \sum_{k=1}^K \frac{X_k^T \mathbf{A} X_k}{X_k^T \mathbf{D} X_k}$

subject to $X \in \{0, 1\}^{N \times K}$,
 $X \mathbf{1}_K = \mathbf{1}_N$.



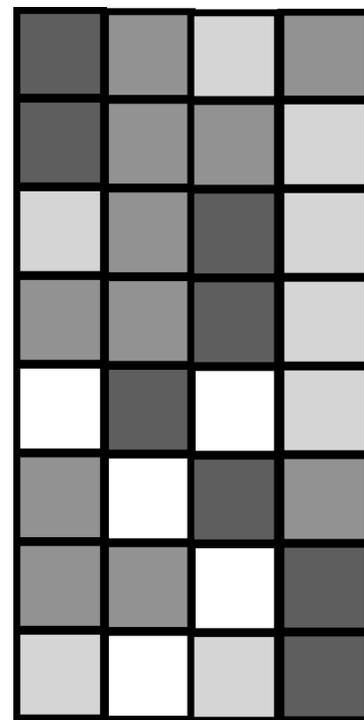
and its orthonormal transforms

Taking the Eigen-decomposition of $\mathbf{D}^{-1}\mathbf{A}$

Set of solutions to the **relaxed** problem

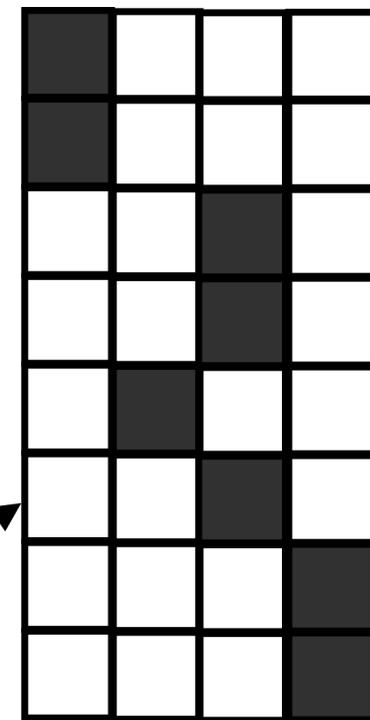
New formulation for spectral clustering

Now we need to **discretize** this solution!



and its orthonormal
transforms

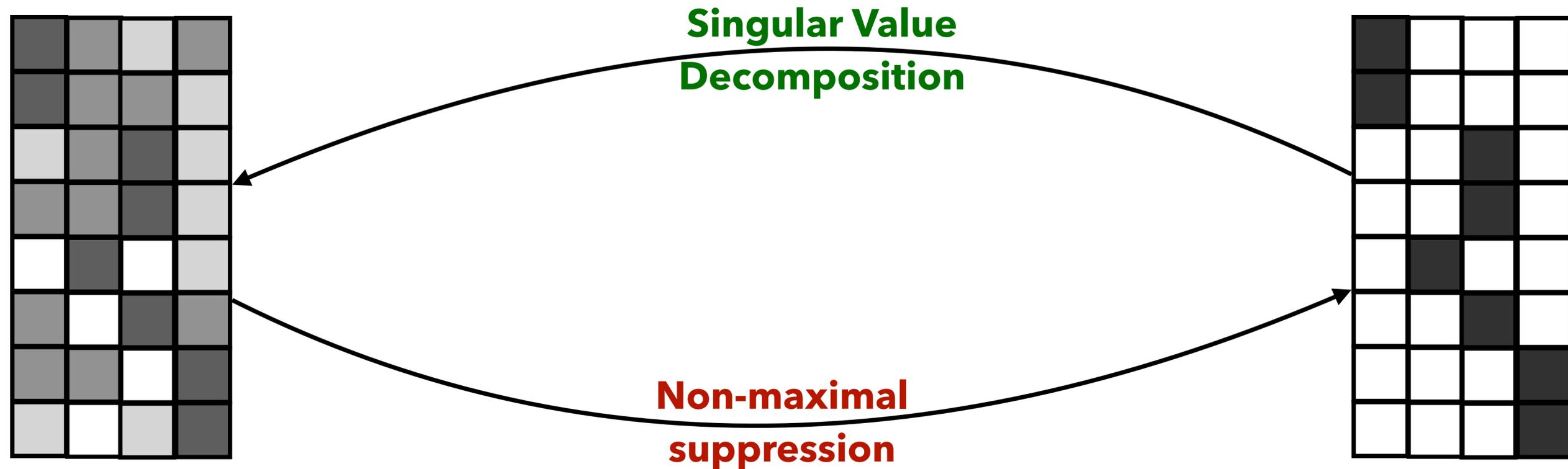
subject to $X \in \{0,1\}^{N \times K},$
 $X \mathbf{1}_K = \mathbf{1}_N.$



Find a matrix which is **discrete** and also close to any one of the **orthonormal transformations** of the relaxed solution

New formulation for spectral clustering

Now we need to **discretize** this solution!

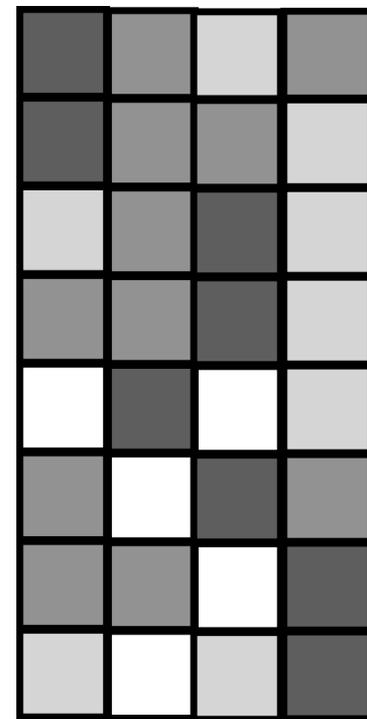


and its orthonormal
transforms

Iterate until convergence

Let us now make it overlap-aware

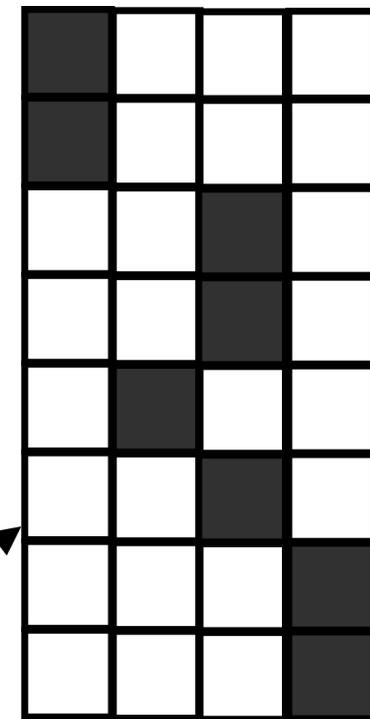
Suppose we have v_{OL}



and its orthonormal
transforms



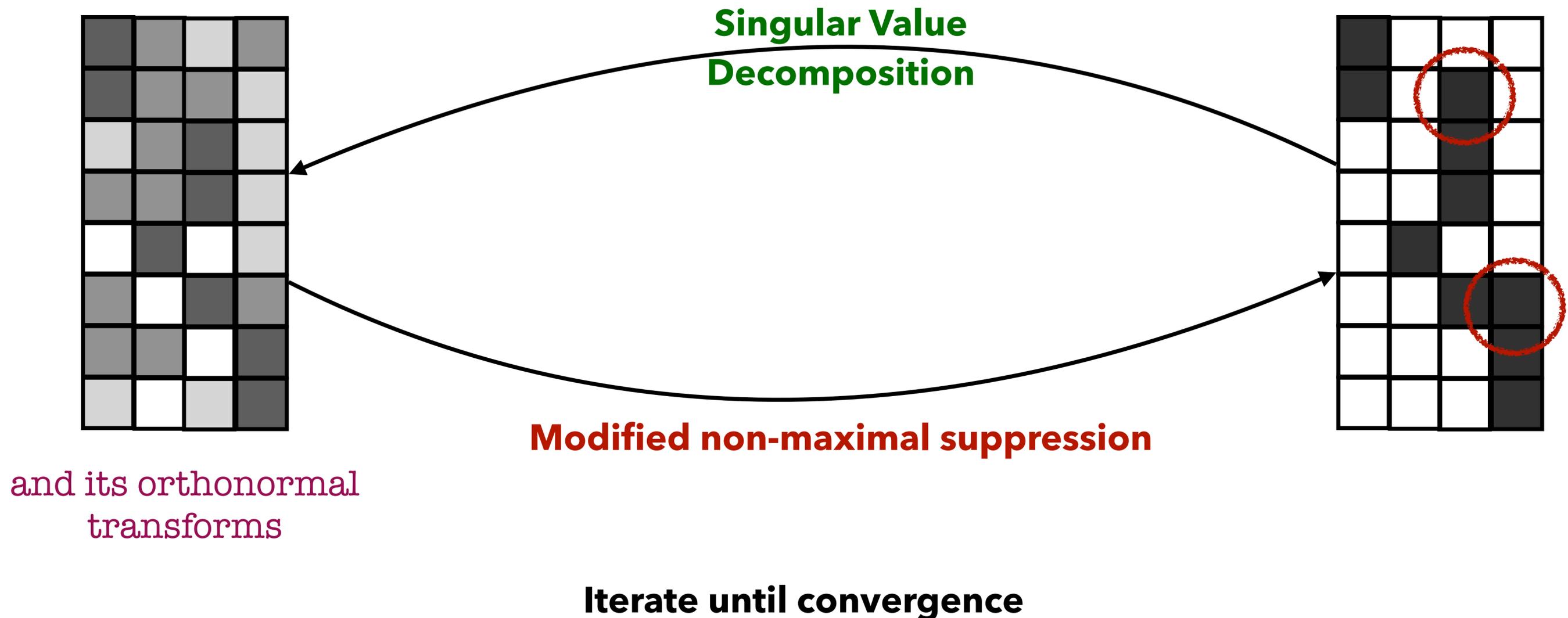
subject to $X \in \{0,1\}^{N \times K}$,
 $X \mathbf{1}_K = \mathbf{1}_N + v_{OL}$.



**Discrete constraint is modified to include
overlap detector output**

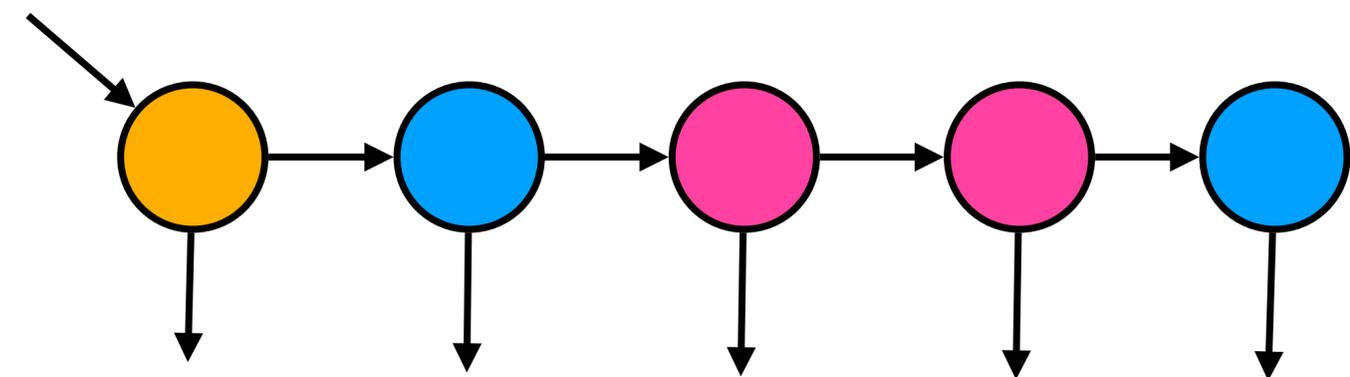
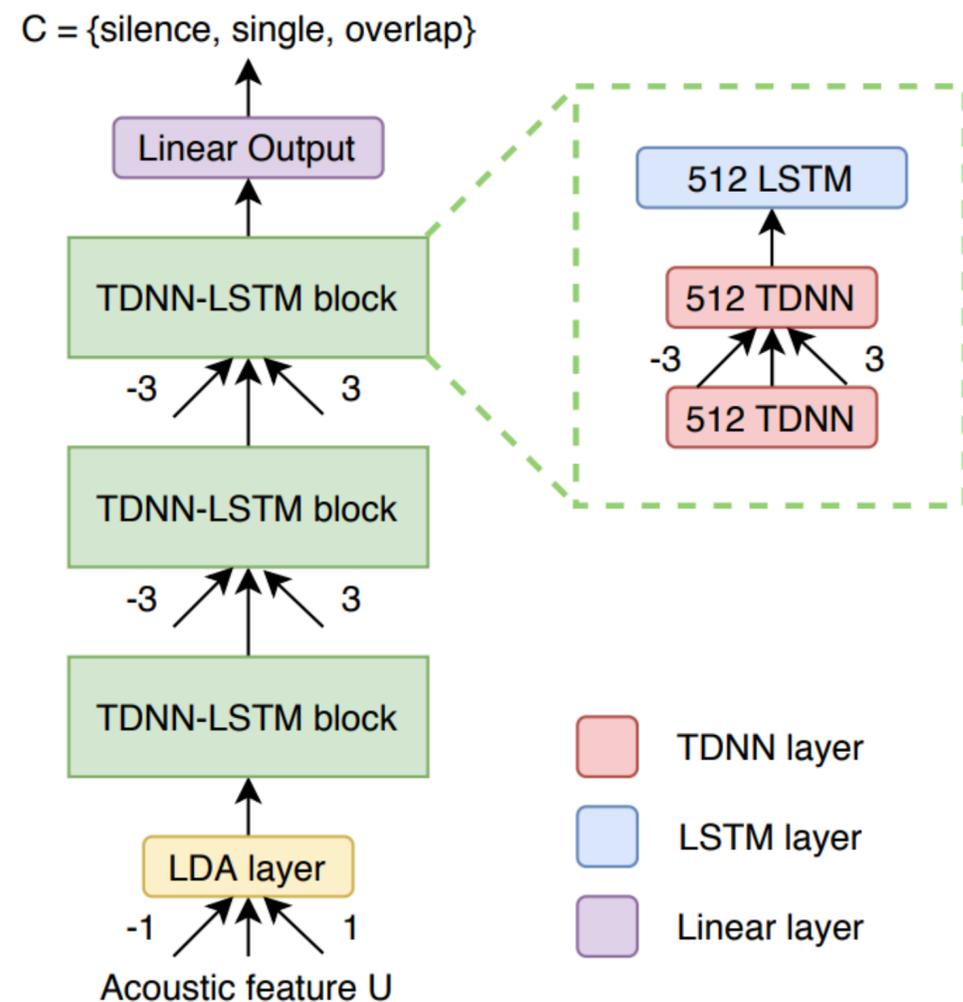
Let us now make it overlap-aware

Modify non-maximal suppression to pick top 2 speakers



Hybrid HMM-DNN overlap detector

(Can also use other methods, e.g. end-to-end)



Emission probability = neural network posteriors

Viterbi decoding used for inference



Results on AMI Mix-Headset eval

12.0% relative improvement over spectral clustering baseline

System	DER
Spectral clustering	26.9
AHC	28.3
VBx	26.2
Overlap-aware SC	24.0

Park et al., "Auto-tuning spectral clustering for speaker diarization using normalized maximum eigengap," IEEE Signal Processing Letters, 2020.

Garcia-Romero et al., "Speaker diarization using deep neural network embeddings," ICASSP 2017.

Díez et al., "Speaker diarization based on Bayesian HMM with eigenvoice priors," Odyssey 2018.

AMI data contains **4-speaker meetings**

Results on AMI Mix-Headset eval

Comparable with other overlap-aware diarization methods

System	DER
VB-based overlap assignment	23.8
Region proposal networks	25.5
Overlap-aware SC	24.0

Bullock, et al., "Overlap-aware diarization: resegmentation using neural end-to-end overlapped speech detection," ICASSP 2020.

Huang et al., "Speaker diarization with region proposal network," ICASSP 2020.

Does not require **matching training data** or **initialization** with other diarization systems.

Results: DER breakdown on AMI eval

System	Missed speech	False alarm	Speaker conf.	DER
AHC/PLDA	19.9	0.0	8.4	26.9
Spectral/cosine	19.9	0.0	7.0	28.3
VBx	19.9	0.0	6.3	26.2
VB-based overlap assignment	13.0	3.6	7.2	23.8
RPN	9.5	7.7	8.3	25.5
Overlap-aware SC	11.3	2.2	10.5	24.0

Results: DER breakdown on AMI eval

Missed speech decreases significantly



System	Missed speech	False alarm	Speaker conf.	DER
AHC/PLDA	19.9	0.0	8.4	26.9
Spectral/cosine	19.9	0.0	7.0	28.3
VBx	19.9	0.0	6.3	26.2
VB-based overlap assignment	13.0	3.6	7.2	23.8
RPN	9.5	7.7	8.3	25.5
Overlap-aware SC	11.3	2.2	10.5	24.0

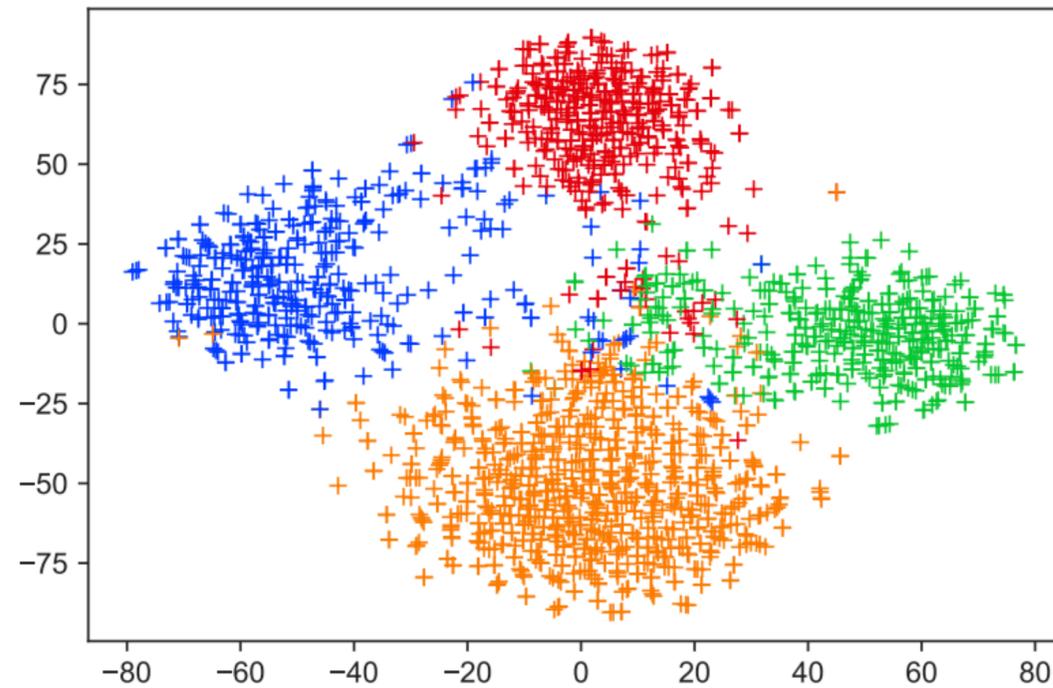
Results: DER breakdown on AMI eval

Speaker confusion increases

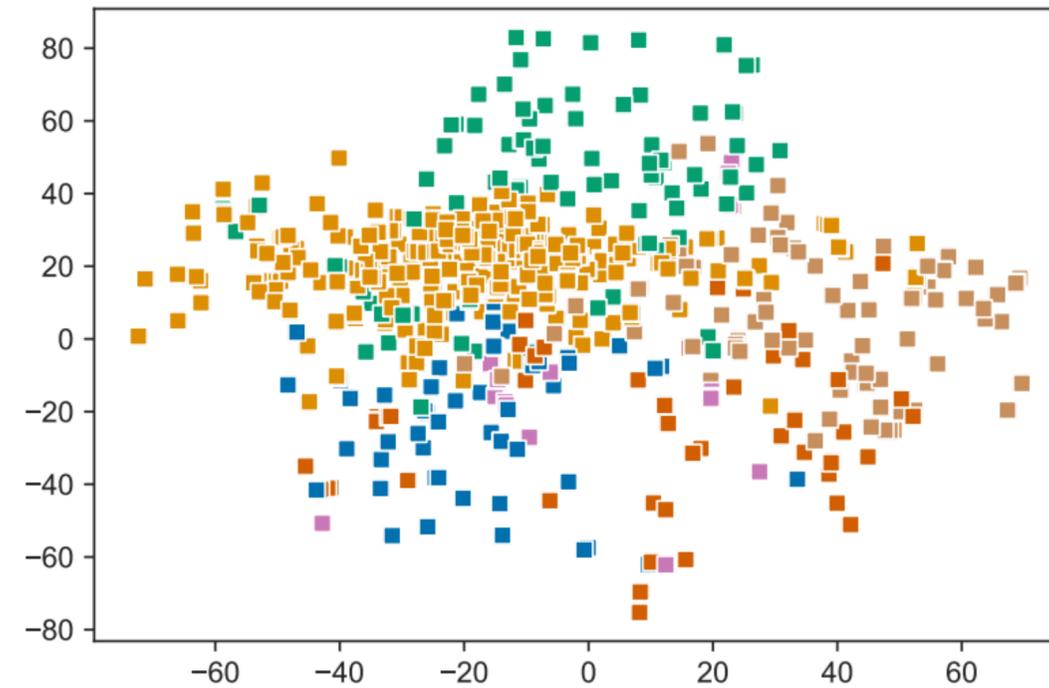


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Need more robust x-vector extractors



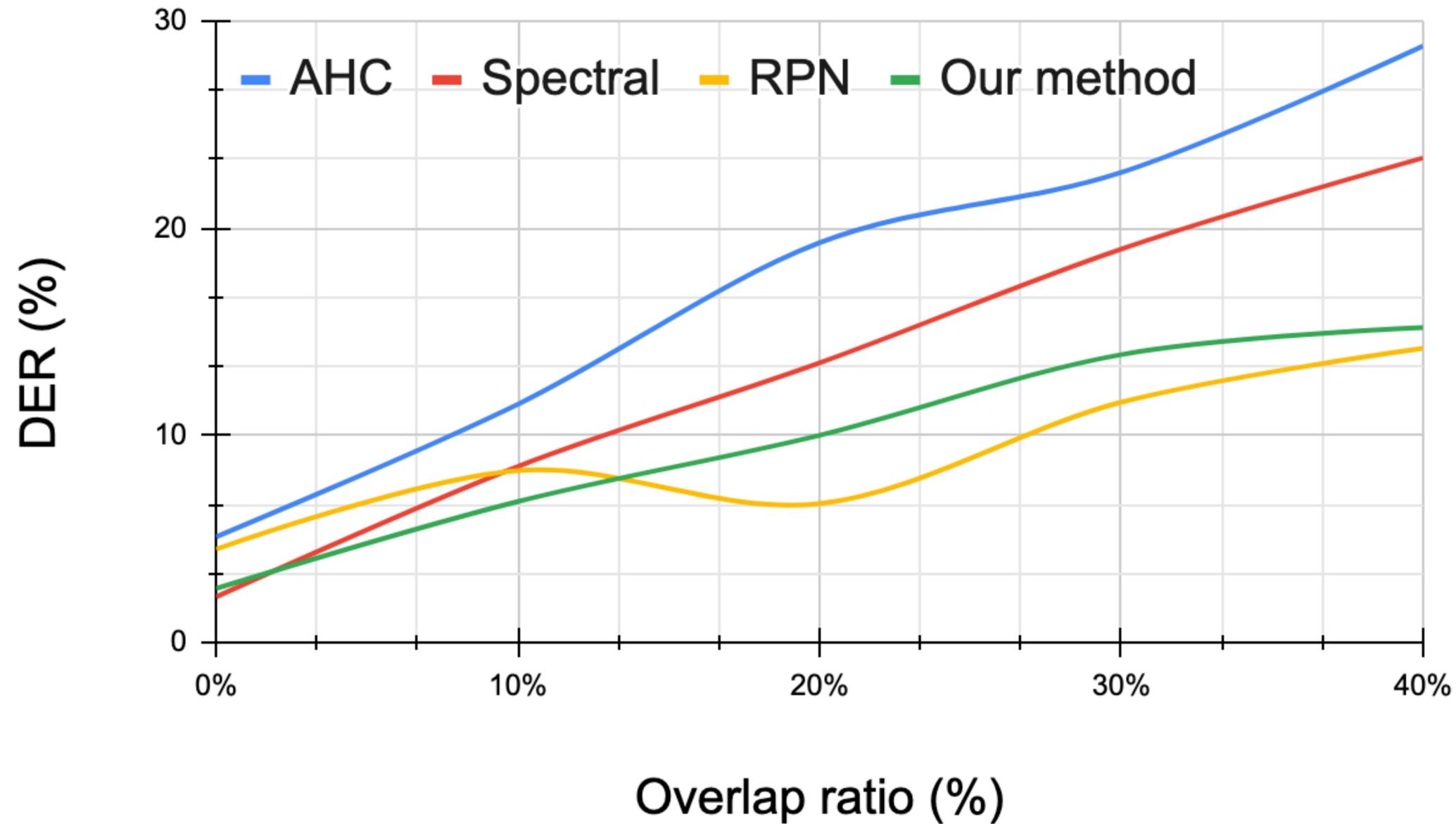
Non-overlapping segments



Overlapping segments

T-SNE plot of x-vector embeddings

More results: DER on LibriCSS



Overlap-aware Diarization

Several new methods proposed recently

Bullock, et al., “Overlap-aware diarization: **resegmentation** using neural end-to-end overlapped speech detection,” ICASSP 2020.

Fujita et al. “**End-to-end neural diarization**: Reformulating speaker diarization as simple multi-label classification,” ArXiv, 2020.

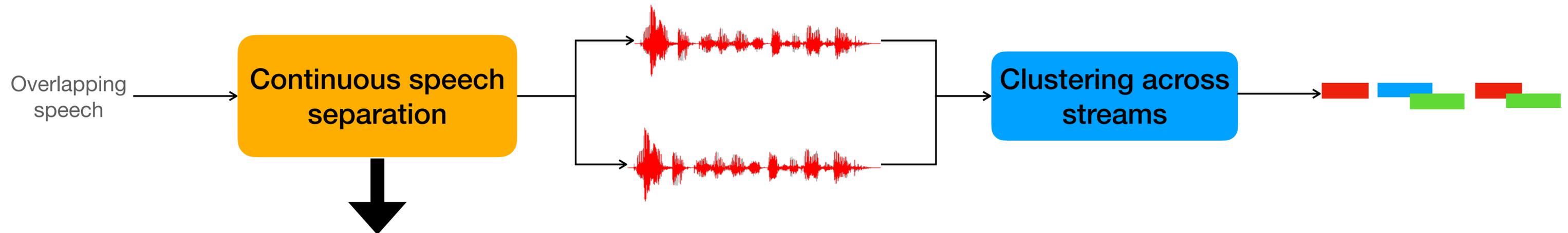
Huang et al., “Speaker diarization with **region proposal network**,” ICASSP 2020.

Kinoshita, et al. **Integrating** end-to-end neural and clustering-based diarization: Getting the best of both worlds. *ArXiv, 2020*.

Medennikov, et al. “**Target speaker voice activity detection**: a novel approach for multispeaker diarization in a dinner party scenario,” Interspeech 2020.

A different paradigm

Separate, then diarize



- Work on small windows (2 to 8 seconds) -- assume at most 2/3 speakers in the window
- Stitch the window output streams

Traditional single-speaker clustering systems can be used in this method!

Results on LibriCSS data

Using 2 different continuous speech separation methods

**Mask-
based MVDR**

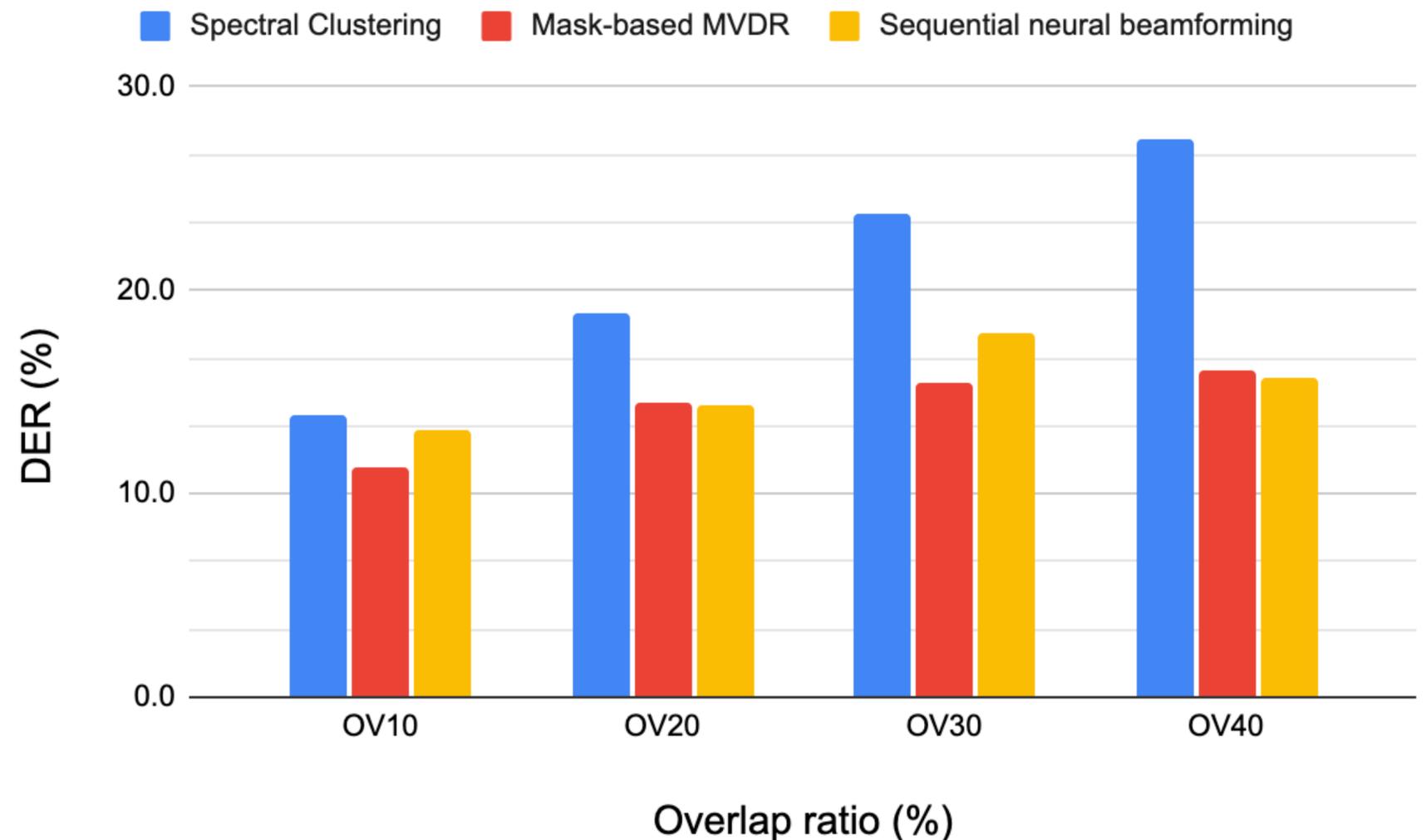
2.4s chunks; 2 streams

Takuya Yoshioka, Hakan Erdogan, Zhuo Chen, and Fil Alleva, "Multi-microphone neural speech separation for far-field multi-talker speech recognition," ICASSP 2018

**Sequential
neural BF**

10s chunks; 3 streams

Zhong-Qiu Wang, Hakan Erdogan, Scott Wisdom, Kevin Wilson, Desh Raj, Shinji Watanabe, Zhuo Chen, and John R. Hershey, "Sequential multi-frame neural beamforming for speech separation and enhancement," IEEE SLT 2021.



Works well in practice

Winner of VoxSRC Track 4 (Diarization)

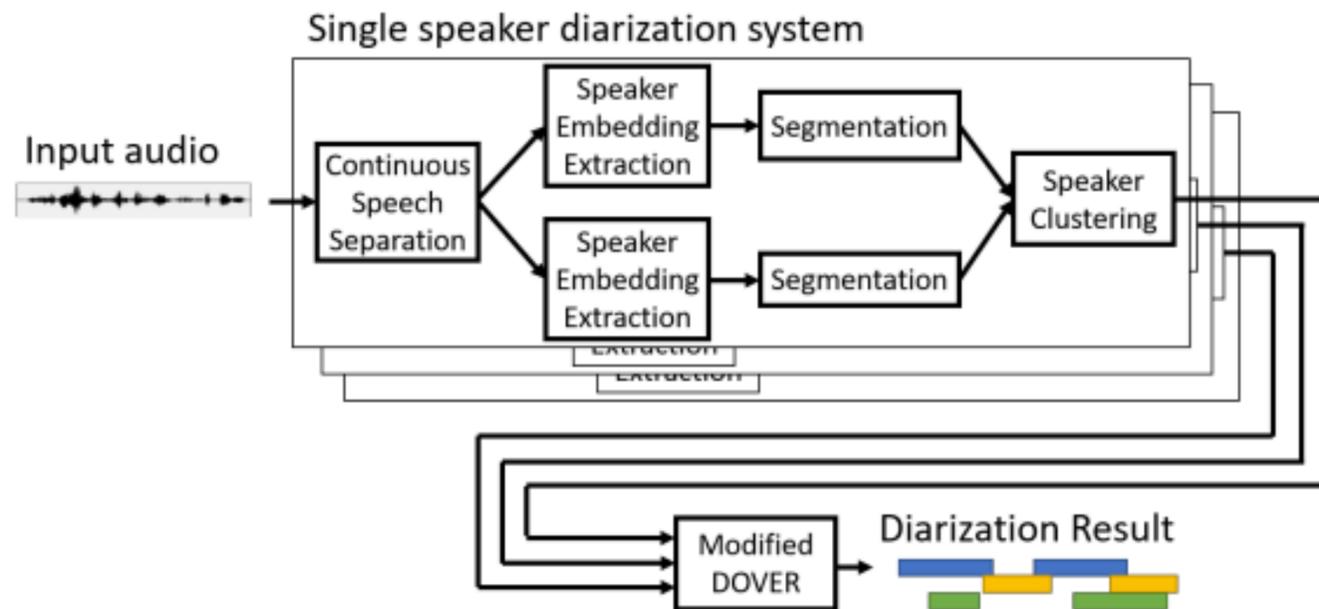


Fig. 1. System Diagram

Team	Method	DER (%)
Huawei	VBx	9.5
Sugou	VB-based overlap assignment	7.2
DKU-DukeECE	VB-based overlap assignment	6.5*
BUT	VBx + overlap handling	4.0
Microsoft	CSS + spectral clustering	3.7

Machine learning tasks benefit from an **ensemble** of systems.

For example, ROVER is a popular combination method for ASR systems.

Problem

Why is it hard to combine diarization systems?

- System outputs may have different number of speaker estimates.
- System outputs are usually in different label space.
- There may not be agreement on whether a region contains overlap.

Solution

DOVER-Lap performs “map and vote”

- System outputs may have different number of speaker estimates.
- System outputs are usually in different label space.
- There may not be agreement on whether a region contains overlap.

Label mapping: Maximal matching algorithm based on a global cost tensor

Raj, D., García-Perera, L.P., Huang, Z., Watanabe, S., Povey, D., Stolcke, A., & Khudanpur, S. DOVER-Lap: A Method for Combining Overlap-aware Diarization Outputs. *IEEE SLT 2021*.

Solution

DOVER-Lap performs “map and vote”

- System outputs may have different number of speaker estimates.
- System outputs are usually in different label space.
- There may not be agreement on whether a region contains overlap.

Label voting: Weighted majority voting considers speaker count in region

Raj, D., García-Perera, L.P., Huang, Z., Watanabe, S., Povey, D., Stolcke, A., & Khudanpur, S. DOVER-Lap: A Method for Combining Overlap-aware Diarization Outputs. *IEEE SLT 2021*.

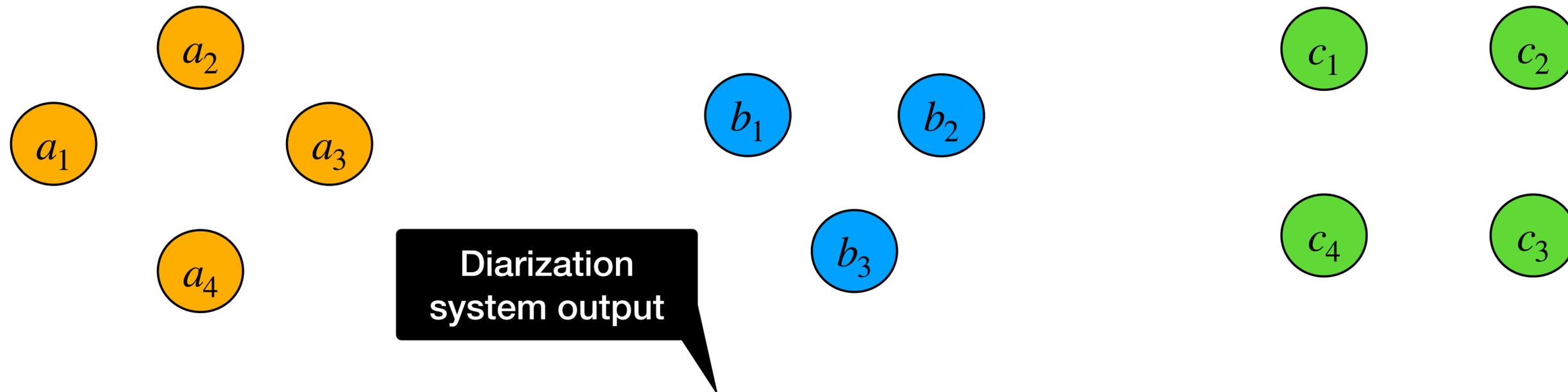
DOVER-Lap extends DOVER

Diarization Output Voting Error Reduction

Hypothesis A e.g. AHC

Hypothesis B e.g. SC

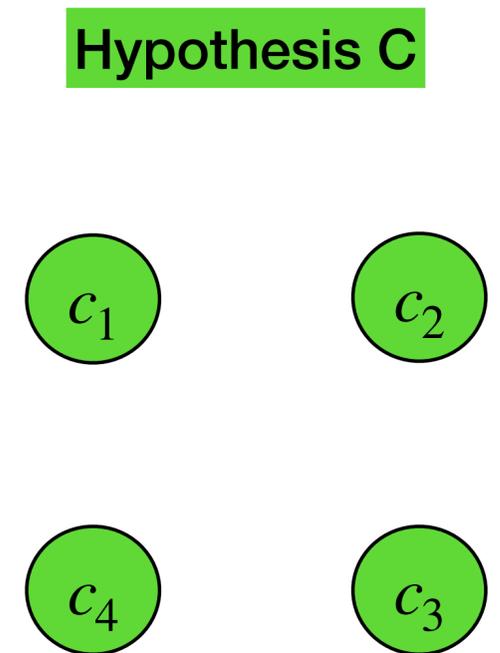
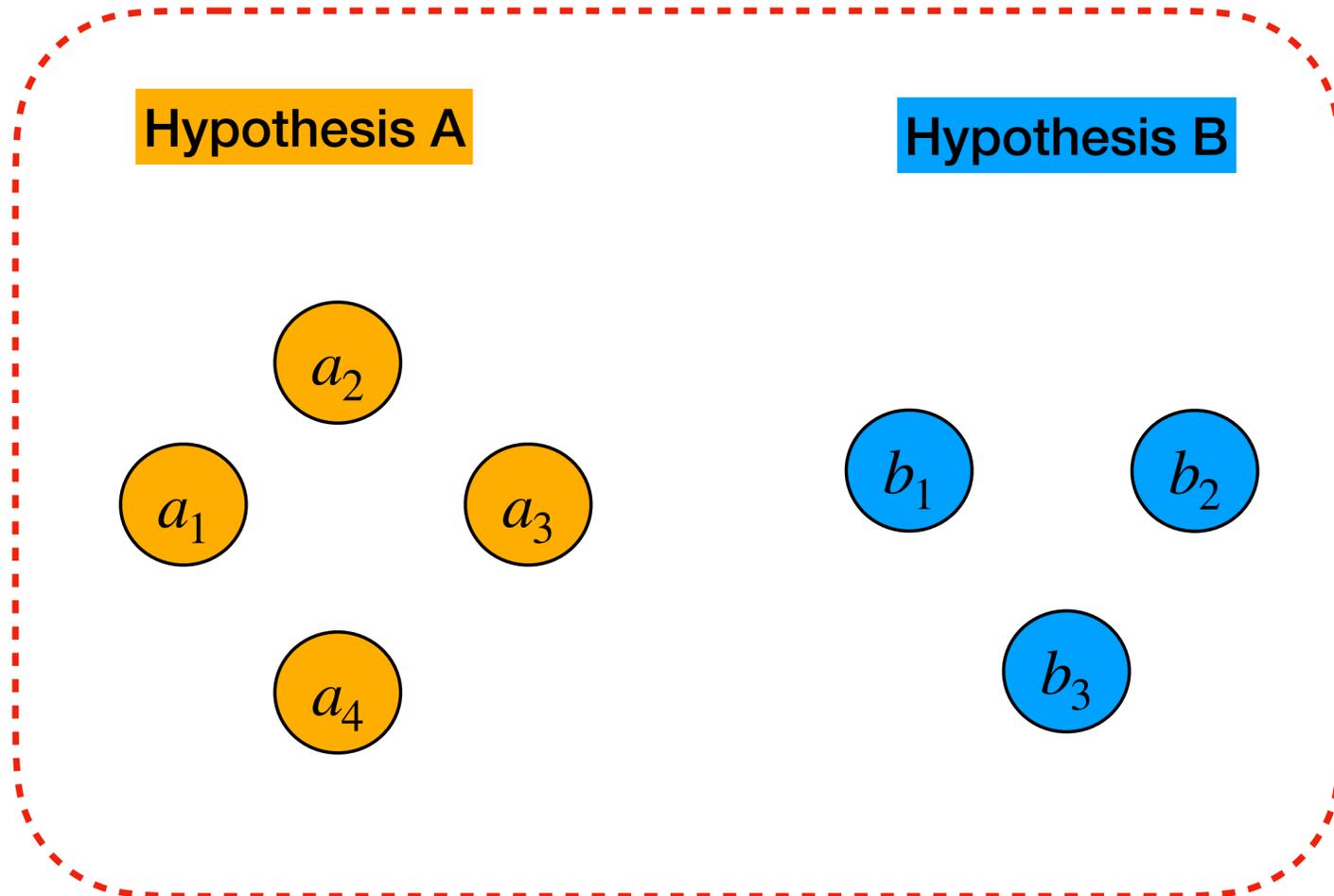
Hypothesis C e.g. VBx



Assumption: The input hypotheses do not contain overlapping segments.

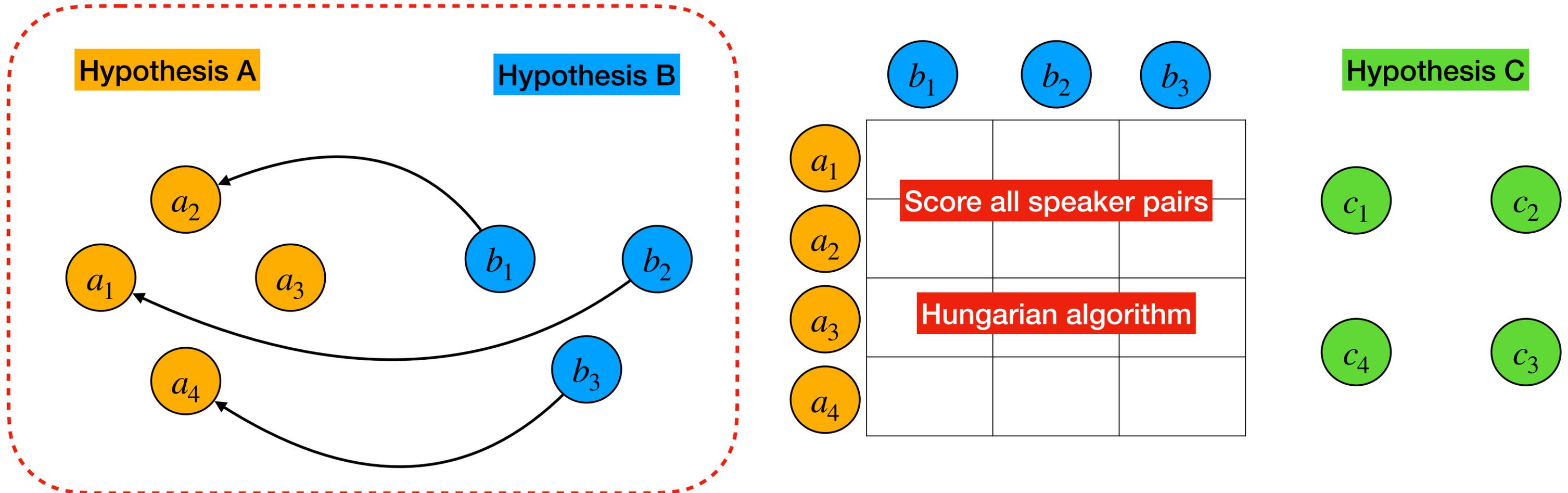
Preliminary: how DOVER works

Pair-wise incremental label mapping



Preliminary: how DOVER works

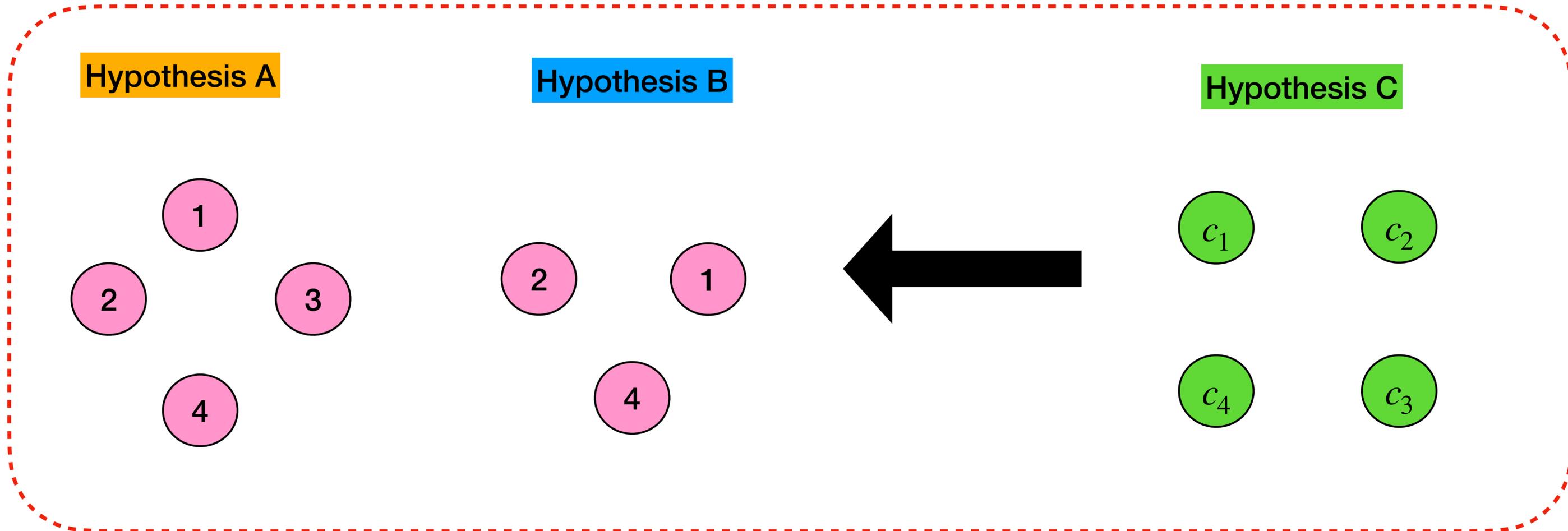
Pair-wise incremental label mapping



This is the same algorithm that is used to map hypothesis to reference for DER computation.

Preliminary: how DOVER works

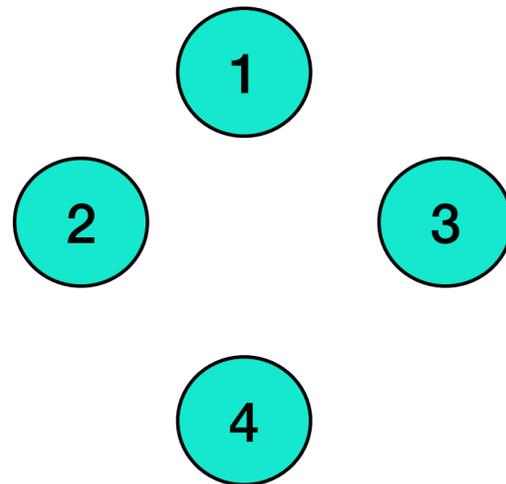
Pair-wise incremental label mapping



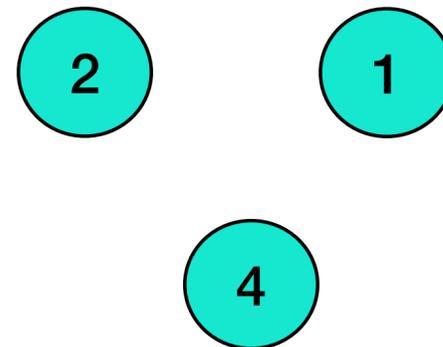
Preliminary: how DOVER works

Pair-wise incremental label mapping

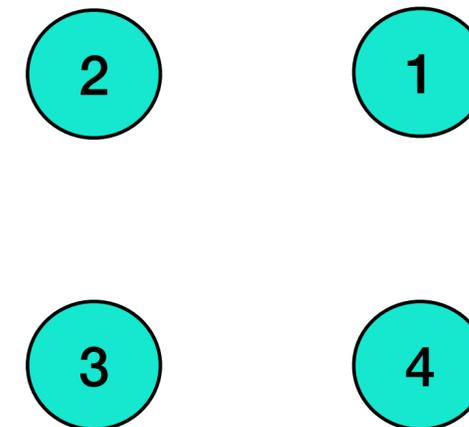
Hypothesis A



Hypothesis B

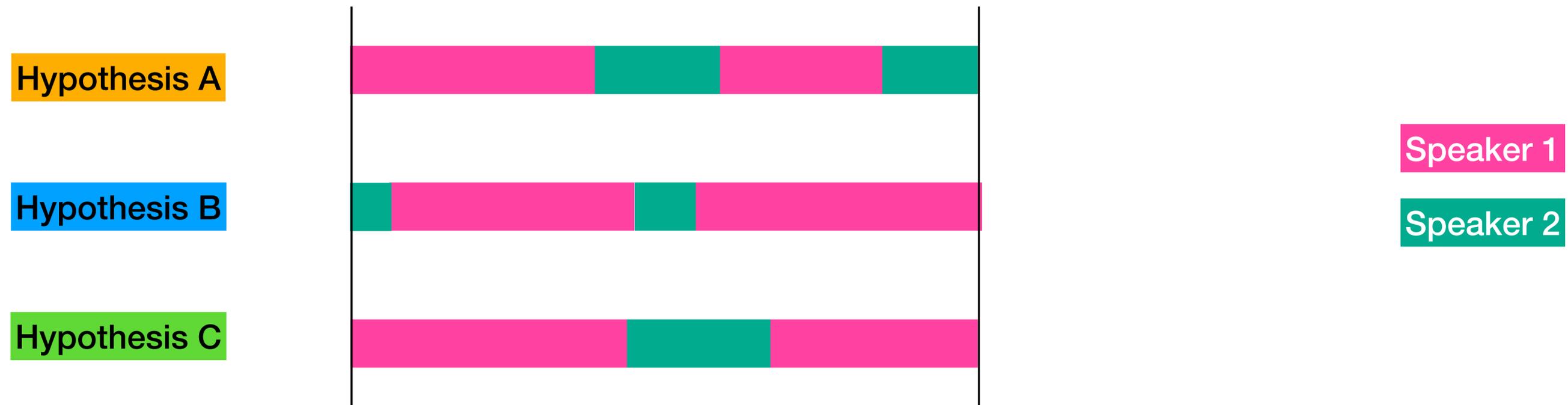


Hypothesis C



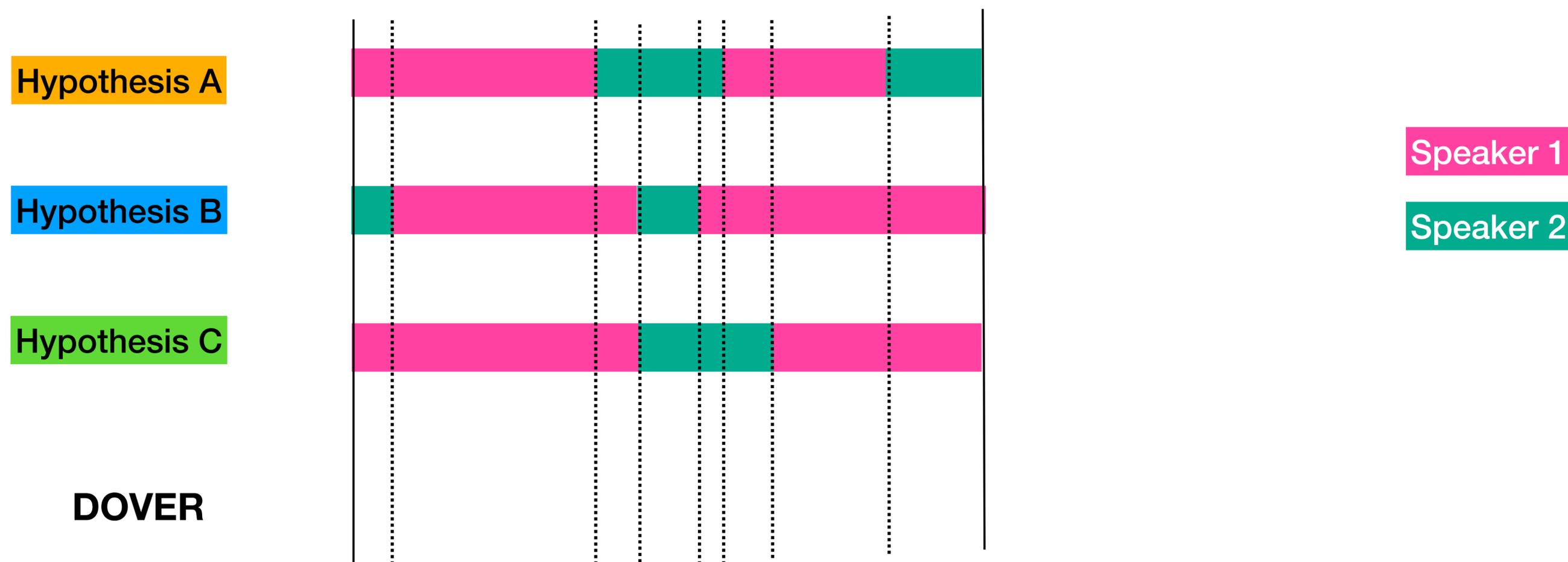
Preliminary: how DOVER works

Label voting using rank-weighting



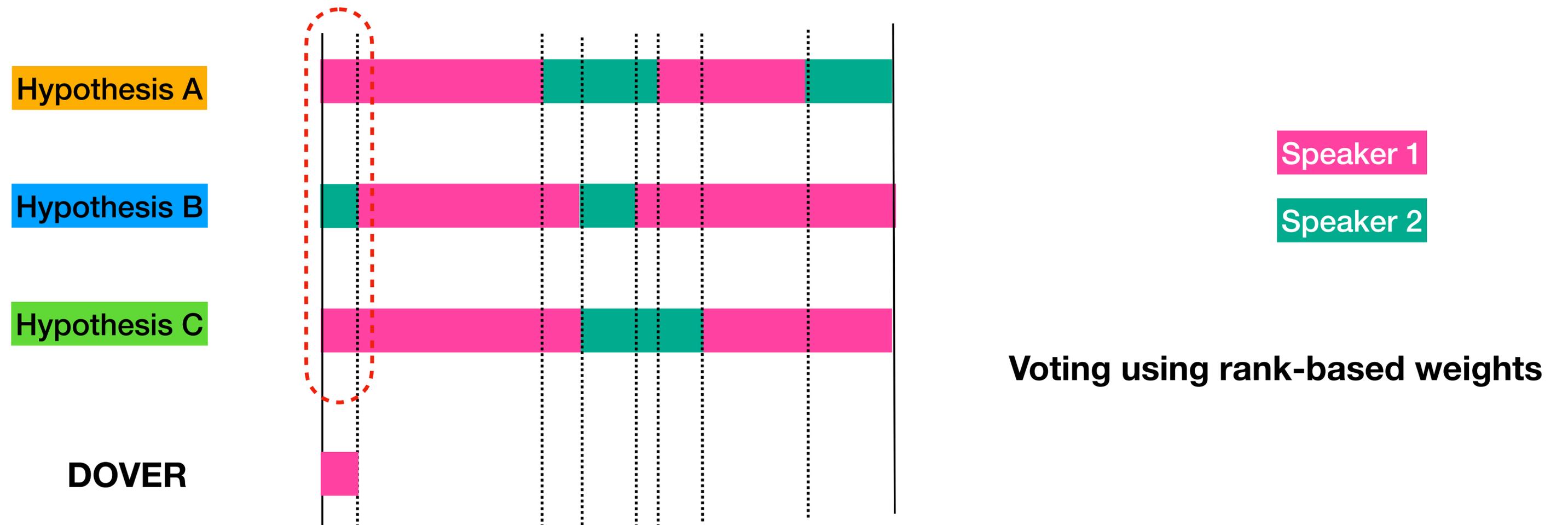
Preliminary: how DOVER works

Label voting using rank-weighting



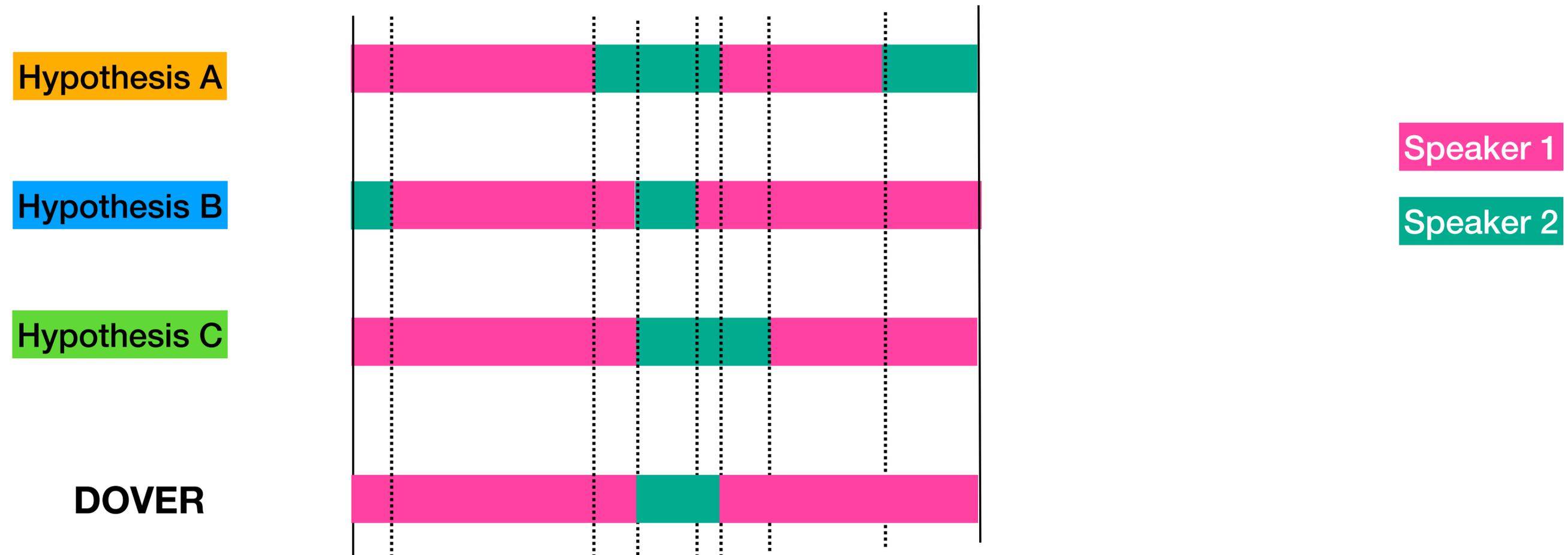
Preliminary: how DOVER works

Label voting using rank-weighting



Preliminary: how DOVER works

Label voting using rank-weighting

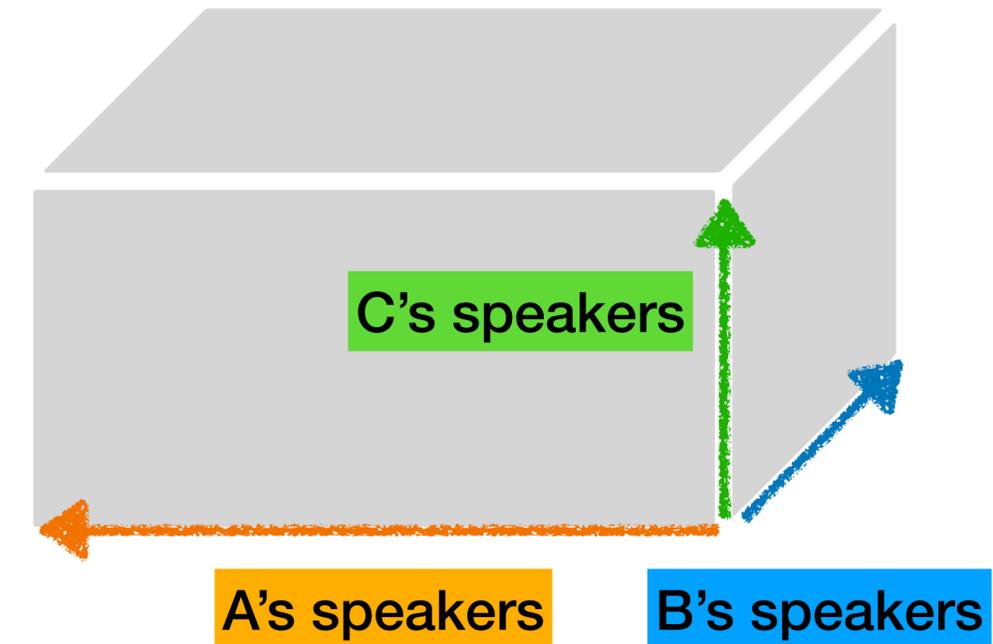
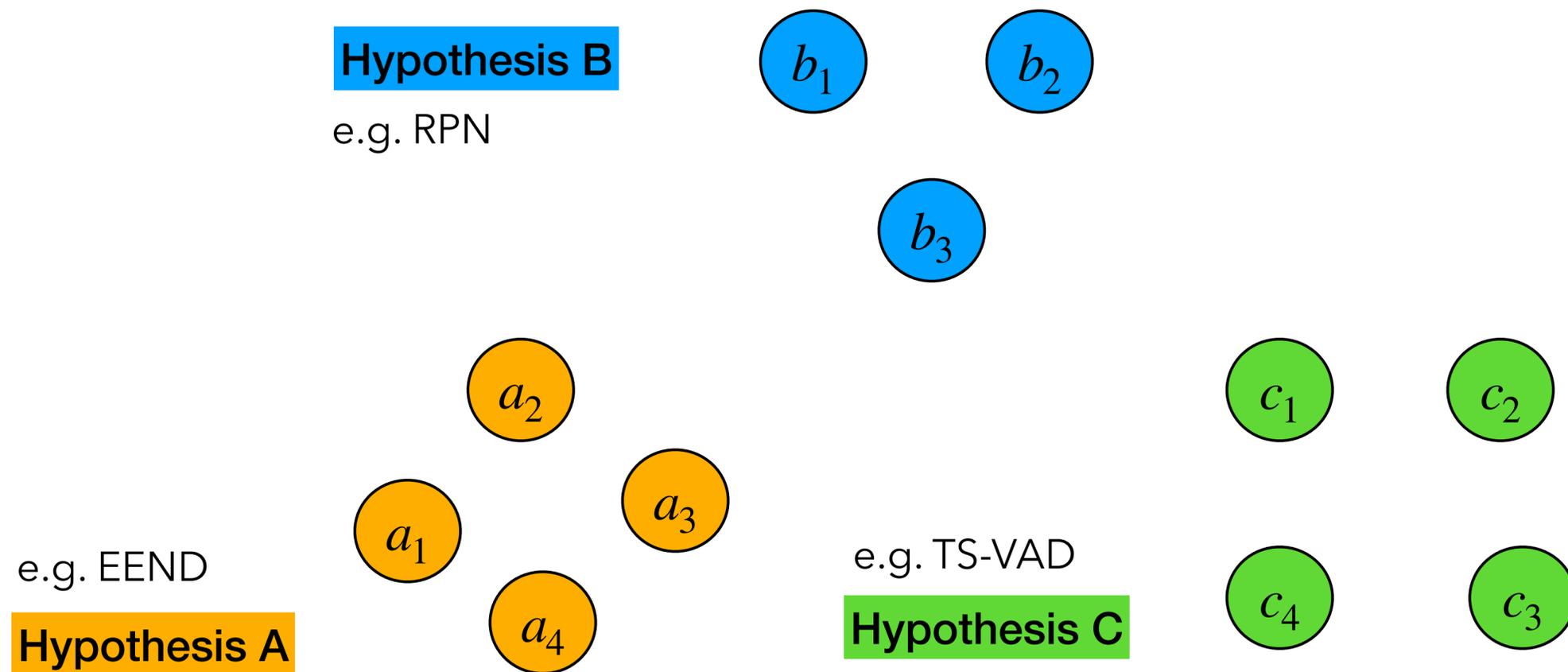


2 limitations of DOVER

1. Incremental pair-wise label assignment does not give **optimal mapping**
2. Voting method does not handle **overlapping speaker segments**

DOVER-Lap label mapping

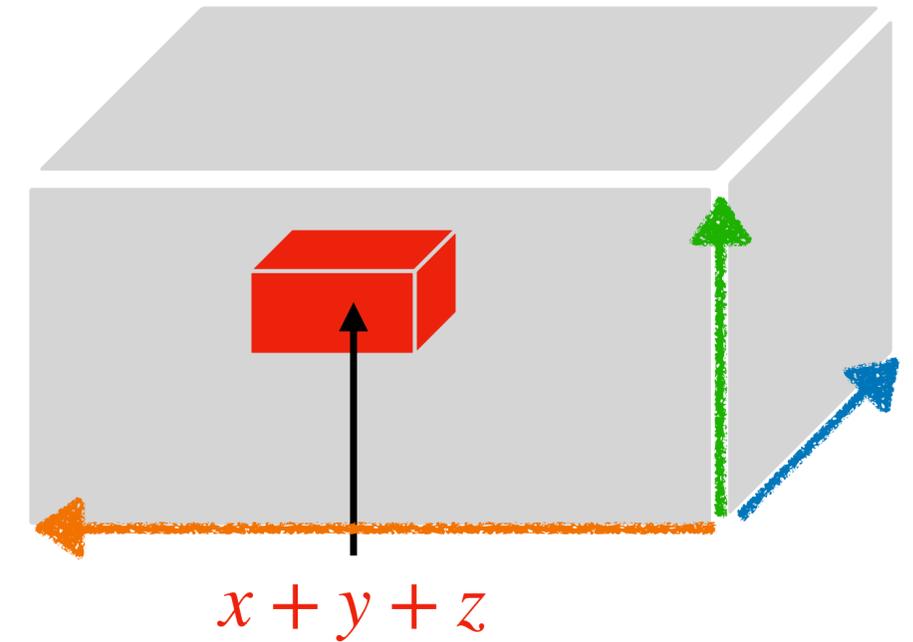
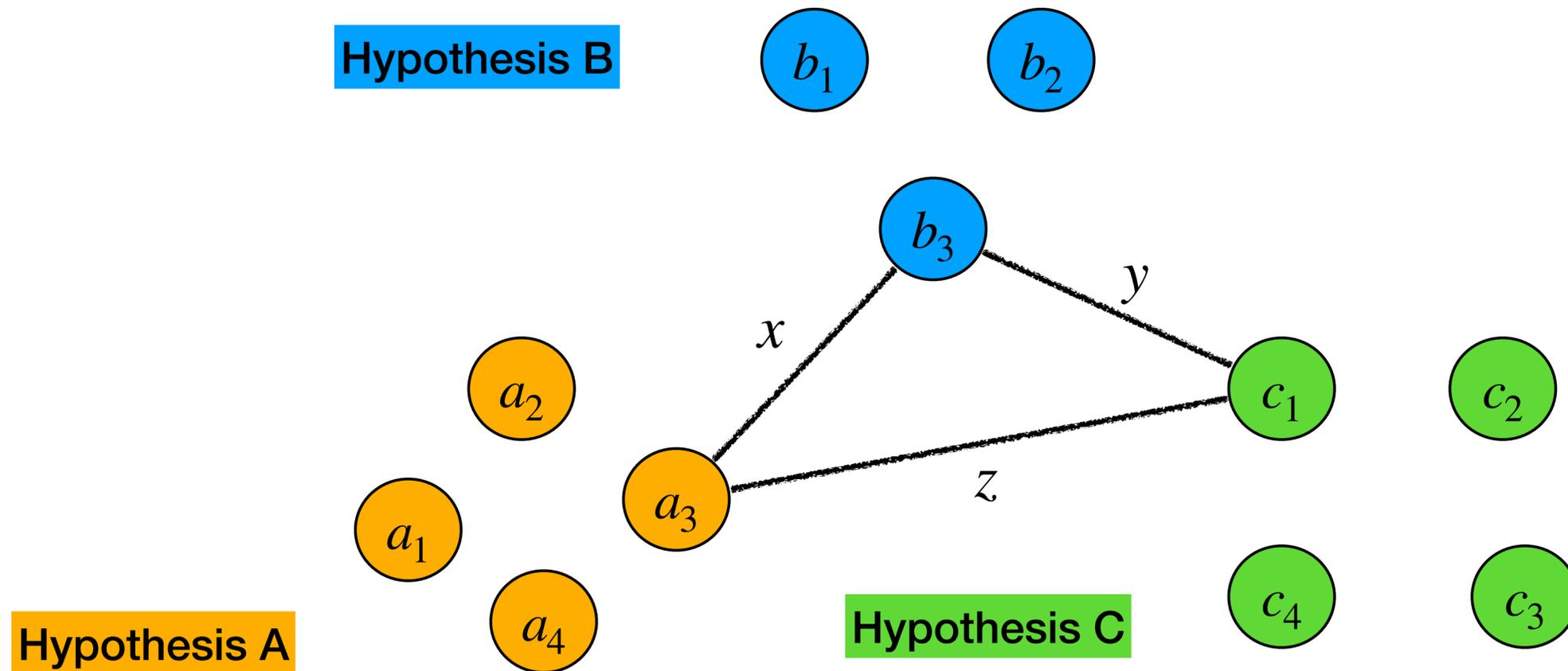
Change incremental method to global



Hypotheses can contain overlapping segments.

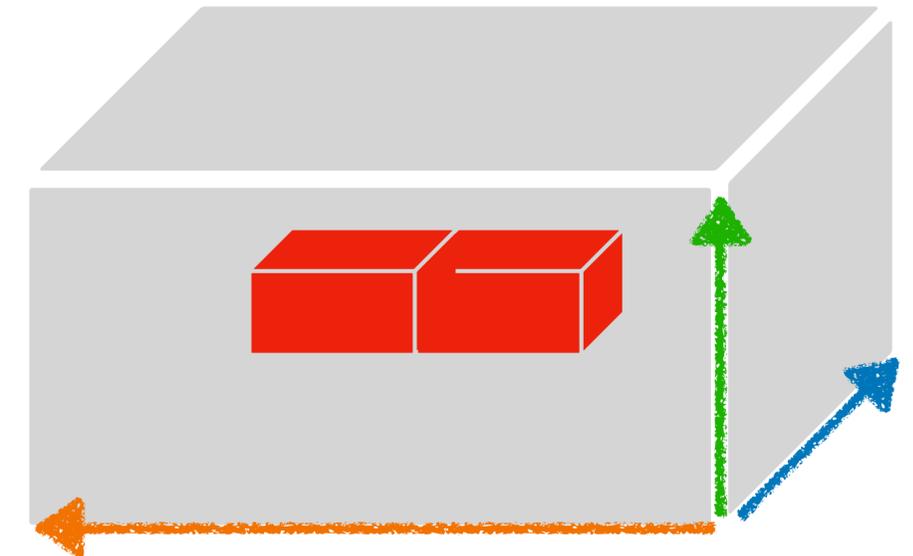
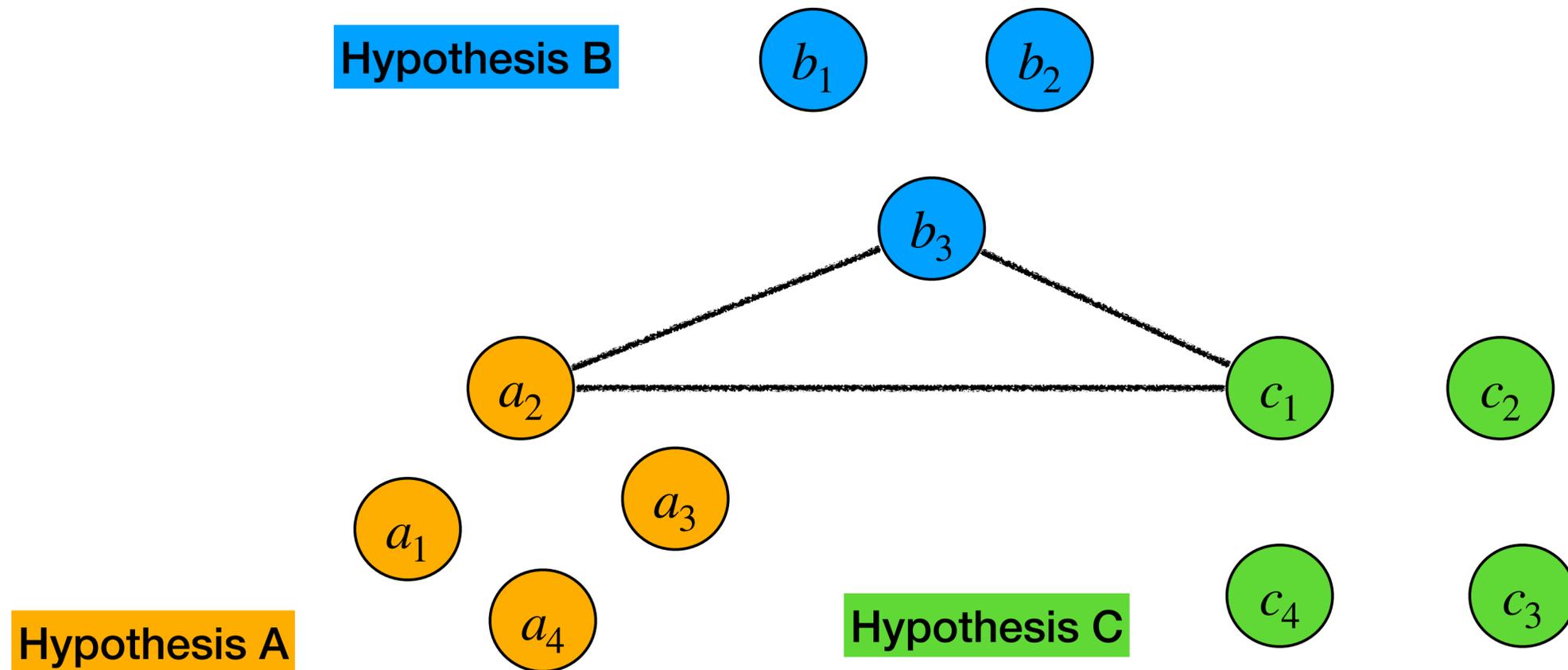
DOVER-Lap label mapping

Compute “tuple costs” for all tuples



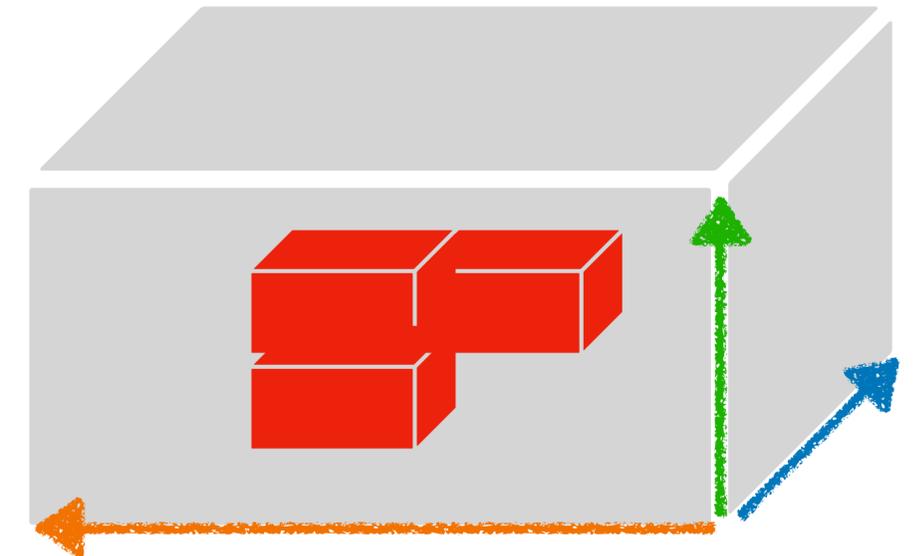
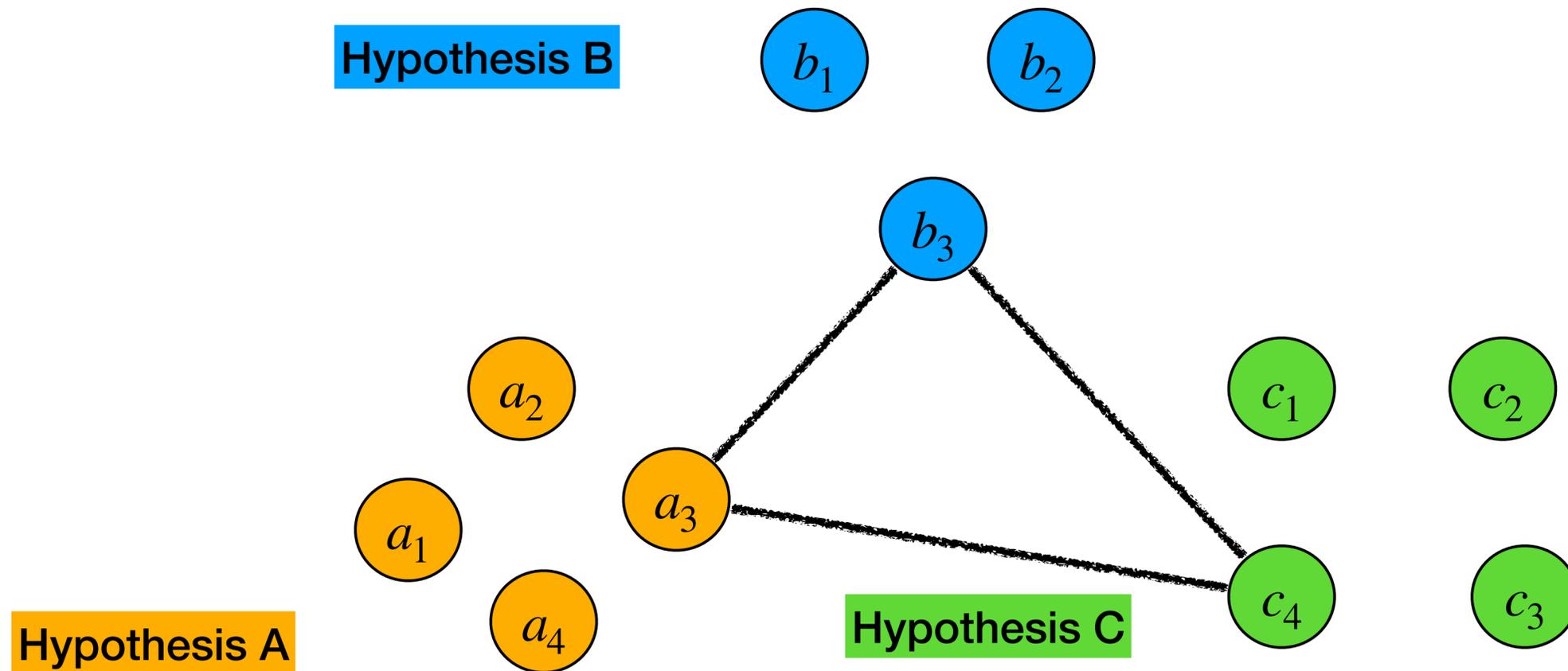
DOVER-Lap label mapping

Compute “tuple costs” for all tuples



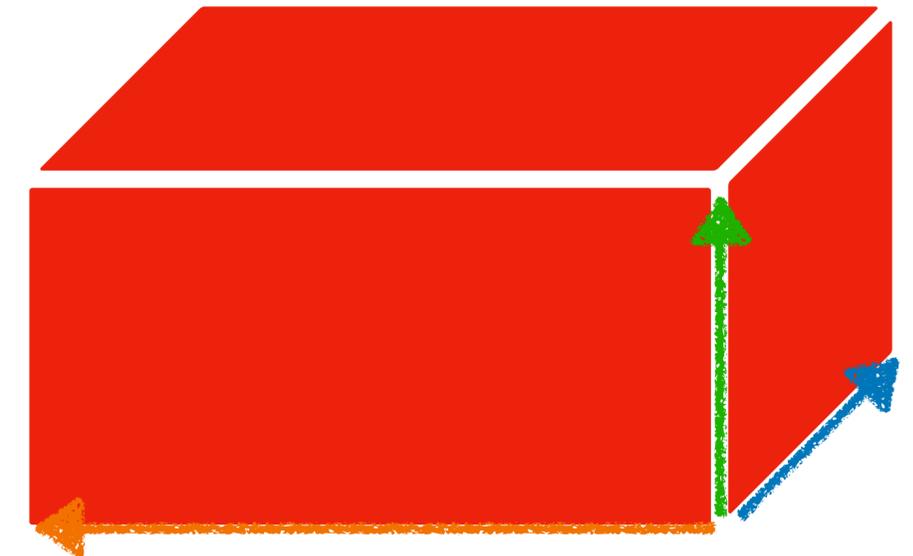
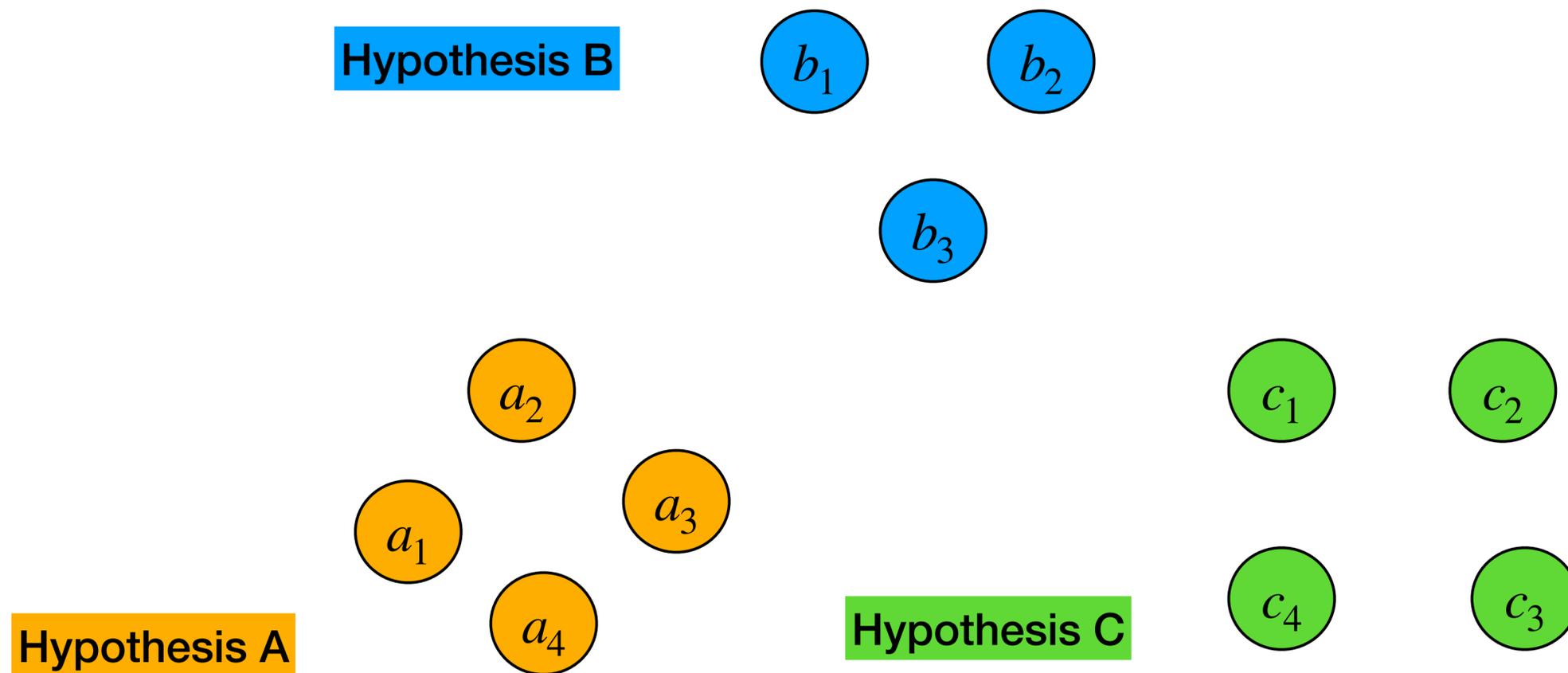
DOVER-Lap label mapping

Compute “tuple costs” for all tuples



DOVER-Lap label mapping

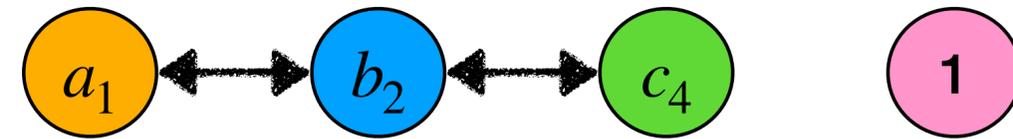
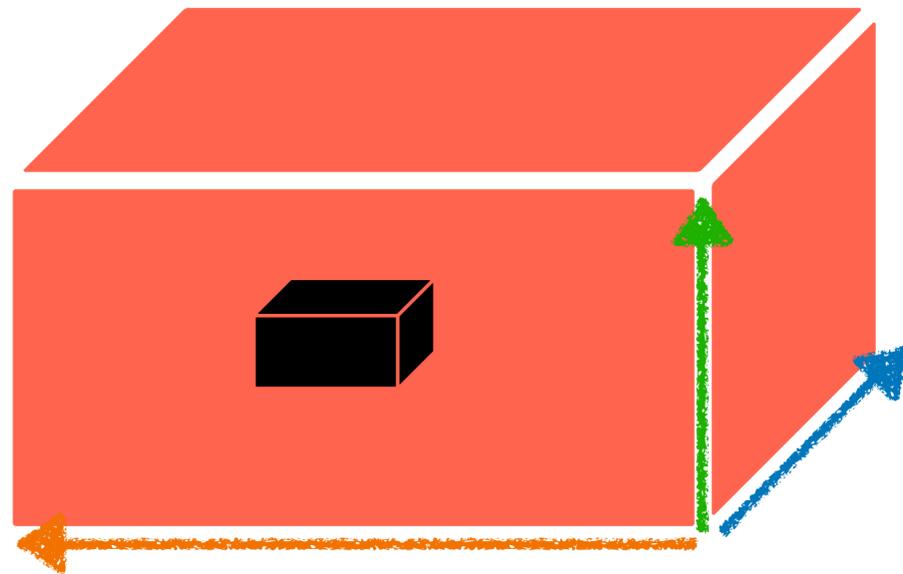
This gives us a “global” cost tensor



Global cost tensor

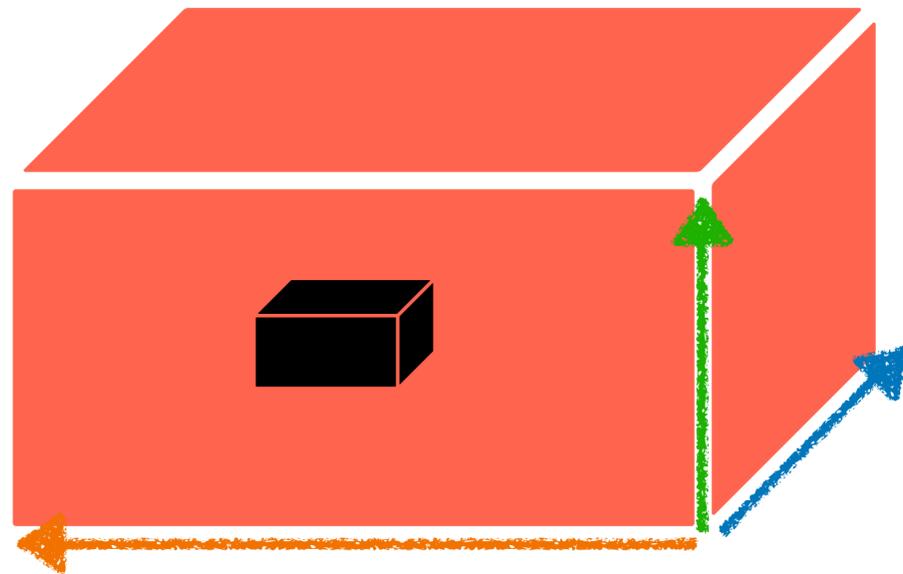
DOVER-Lap label mapping

Pick tuple with the lowest cost and assign them same label

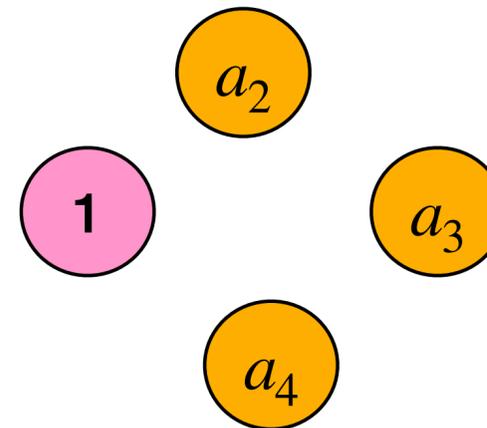


DOVER-Lap label mapping

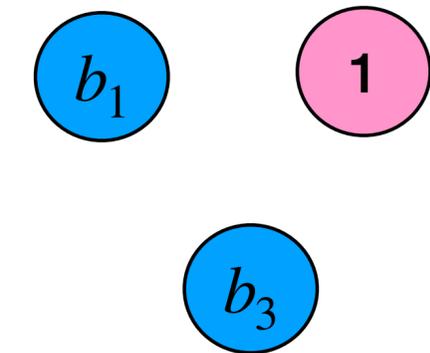
Pick tuple with the lowest cost and assign them same label



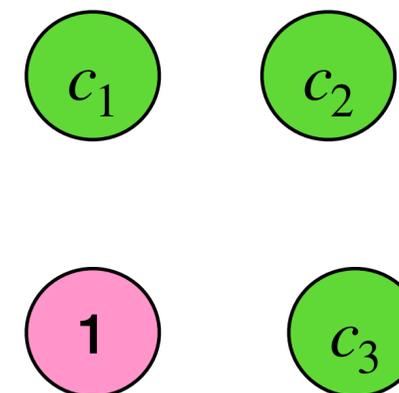
Hypothesis A



Hypothesis B

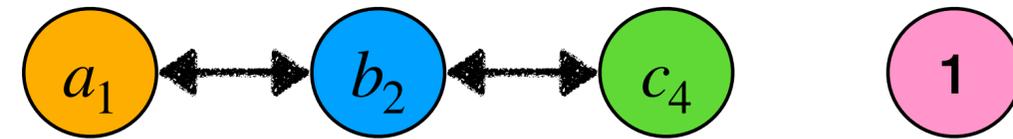
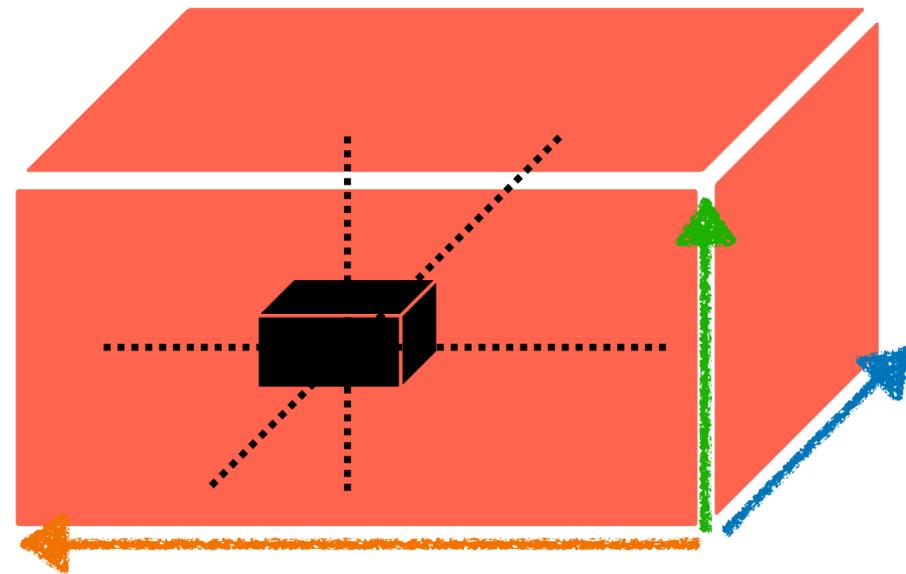


Hypothesis C



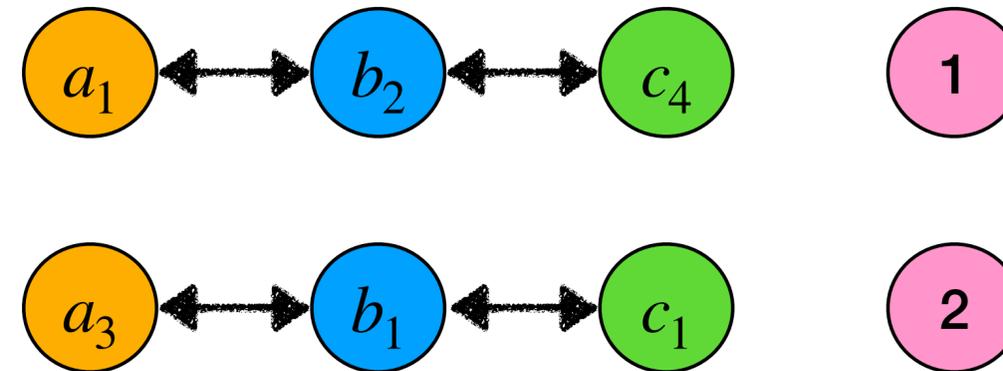
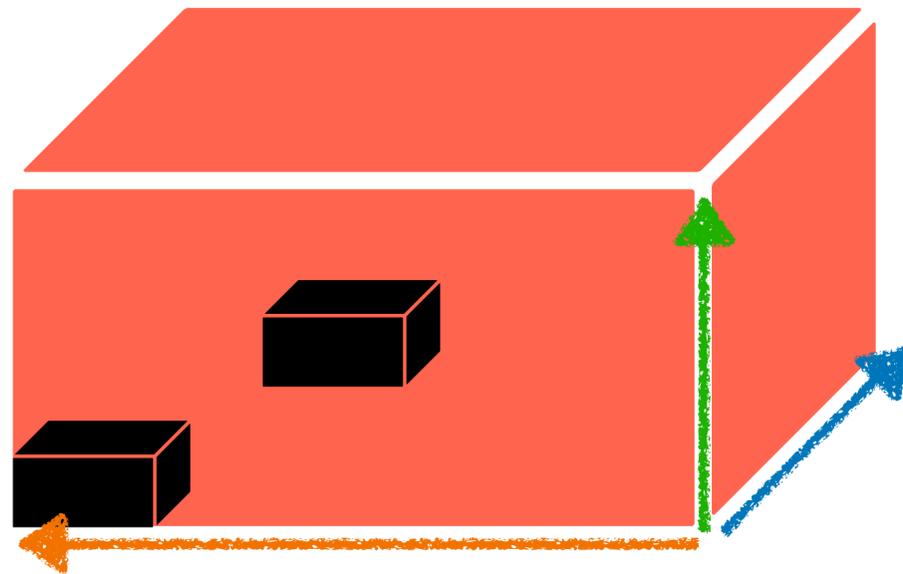
DOVER-Lap label mapping

Discard all tuples containing these labels



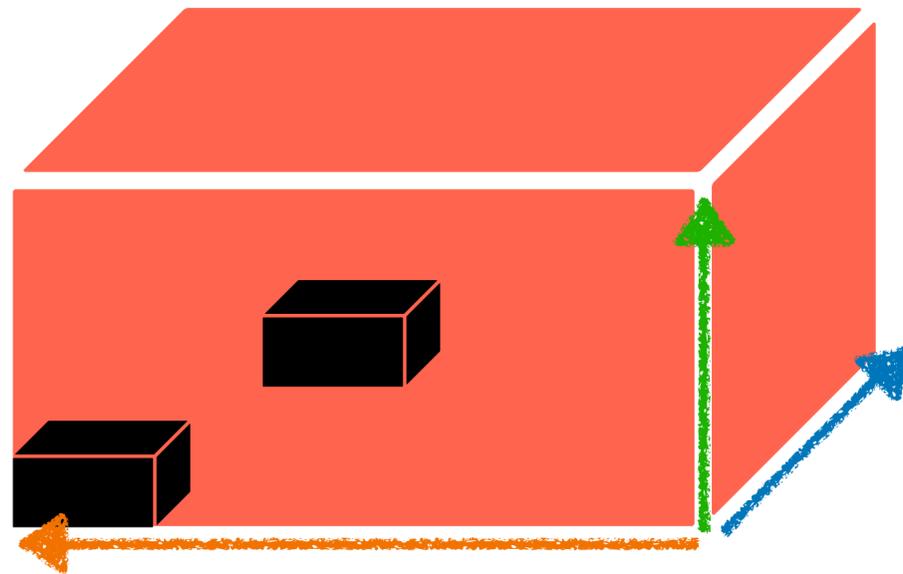
DOVER-Lap label mapping

Pick tuple with lowest cost in remaining tensor

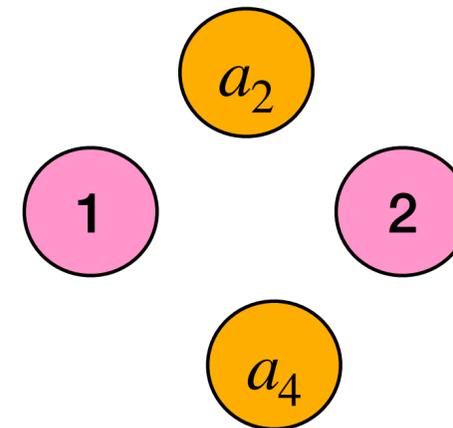


DOVER-Lap label mapping

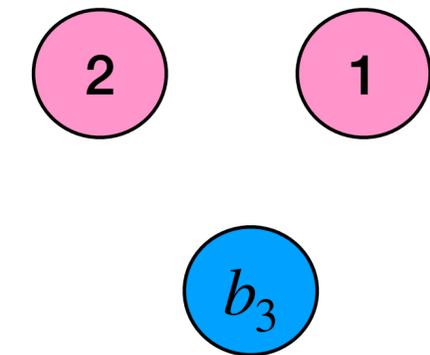
Pick tuple with lowest cost in remaining tensor



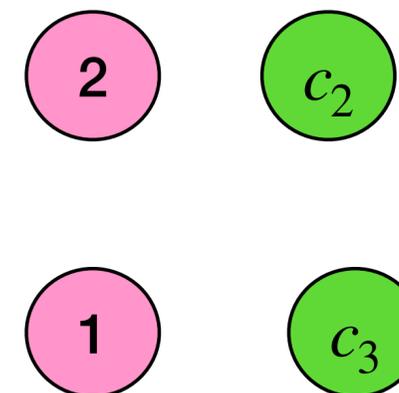
Hypothesis A



Hypothesis B

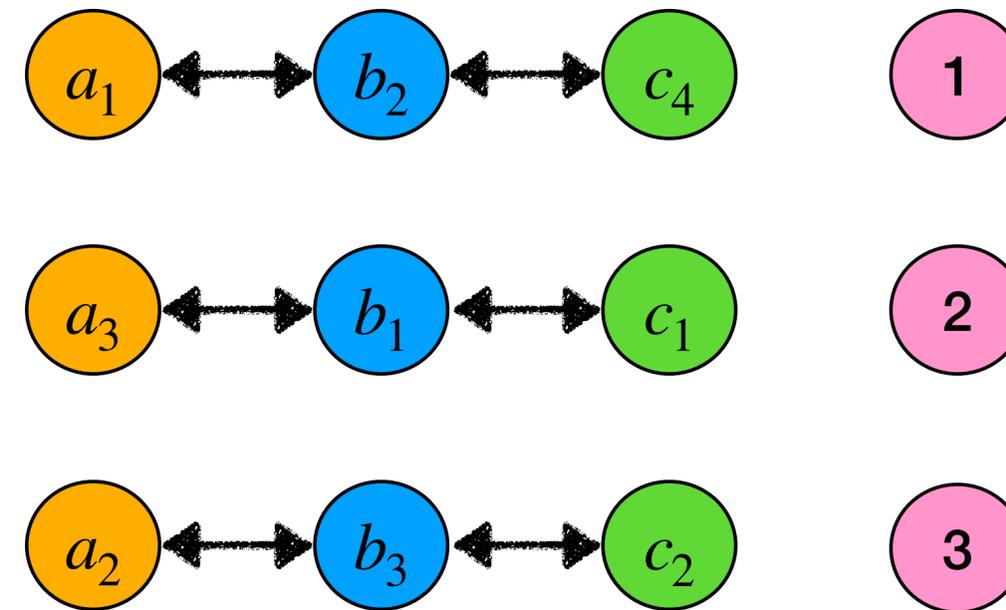
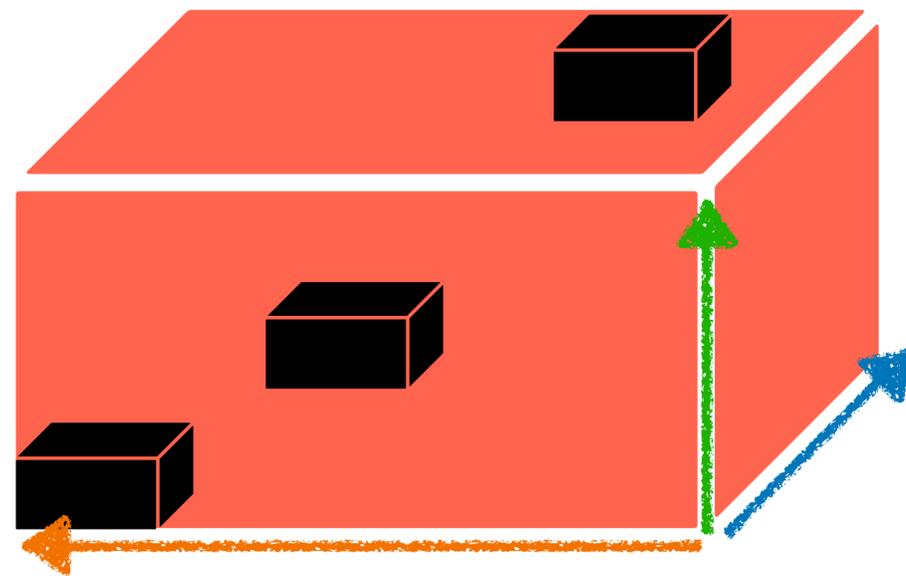


Hypothesis C



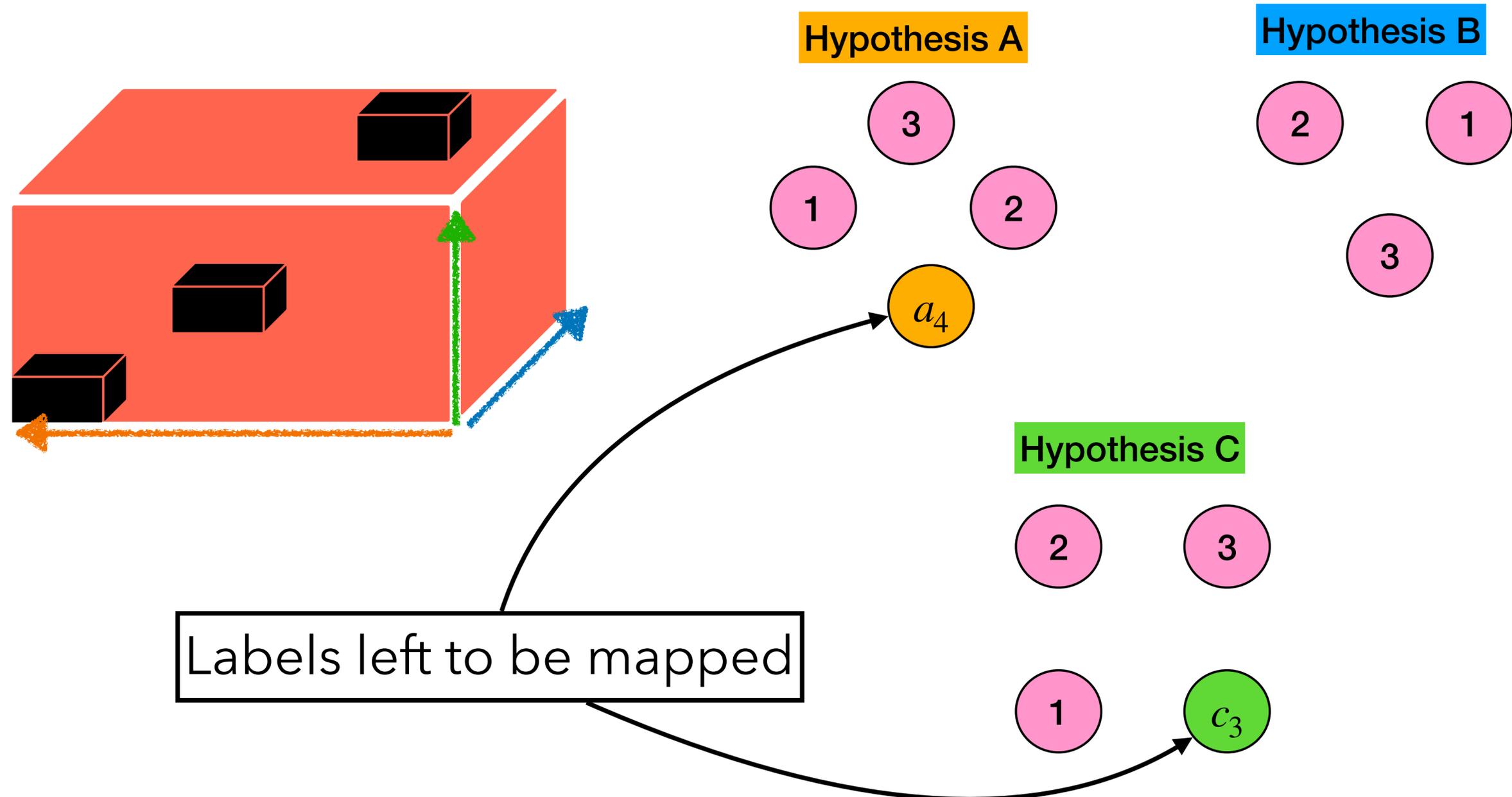
DOVER-Lap label mapping

Repeat until no tuples are remaining



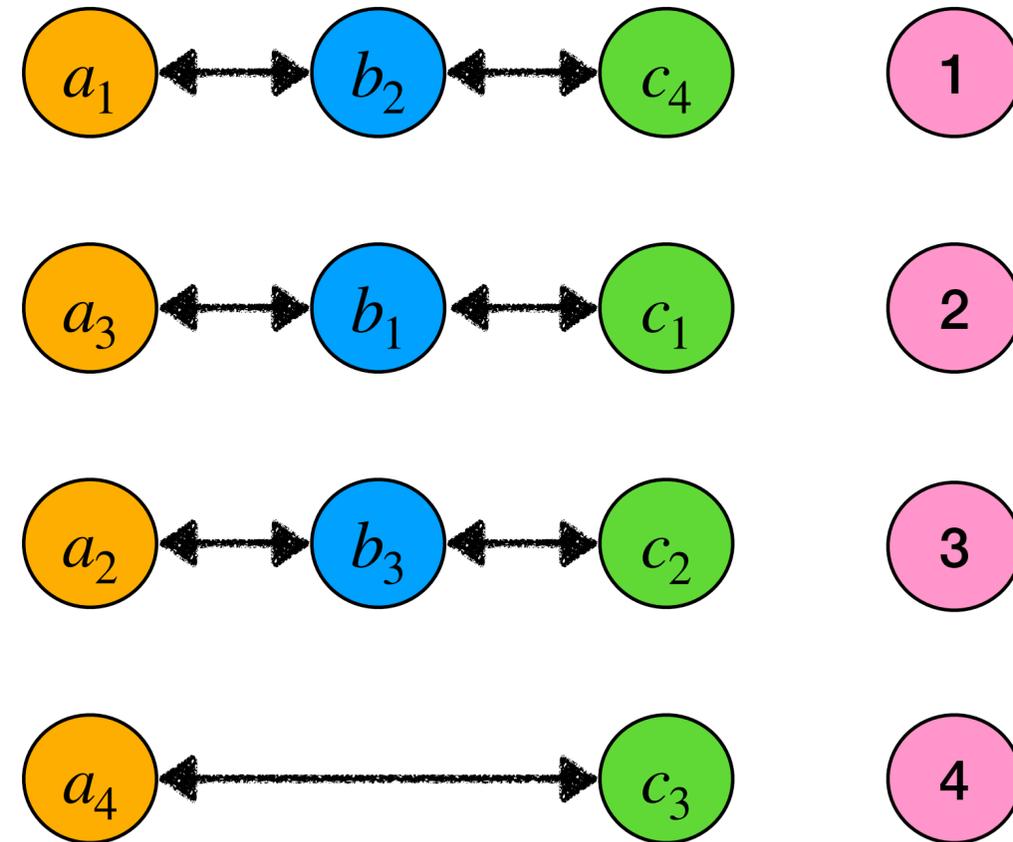
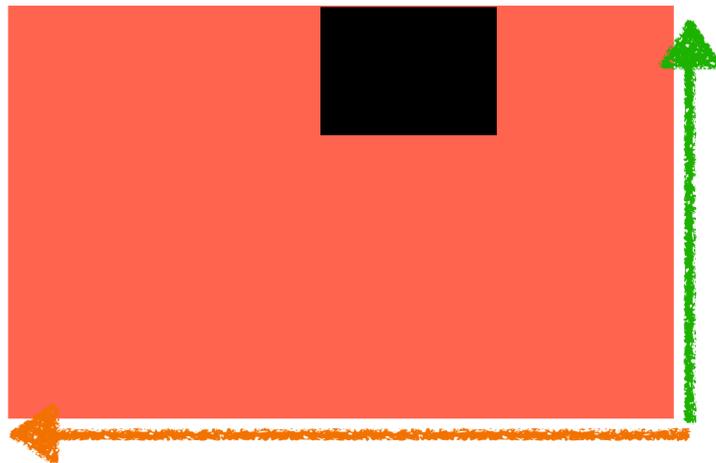
DOVER-Lap label mapping

Repeat until no tuples are remaining



DOVER-Lap label mapping

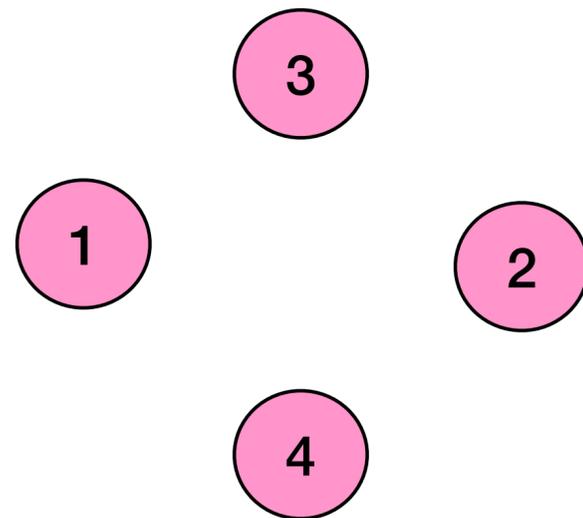
If no tuples remaining but labels left to be mapped, remove filled dimensions and repeat



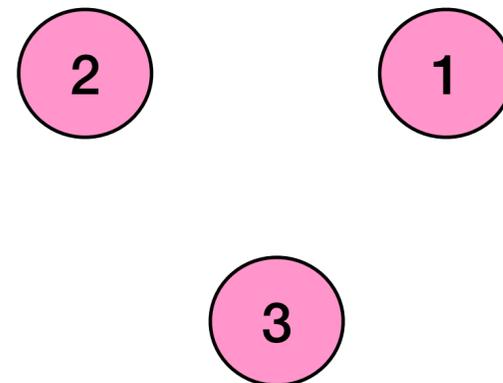
DOVER-Lap label mapping

Final mapped labels

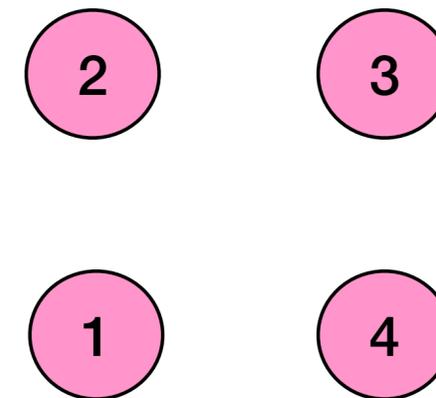
Hypothesis A



Hypothesis B

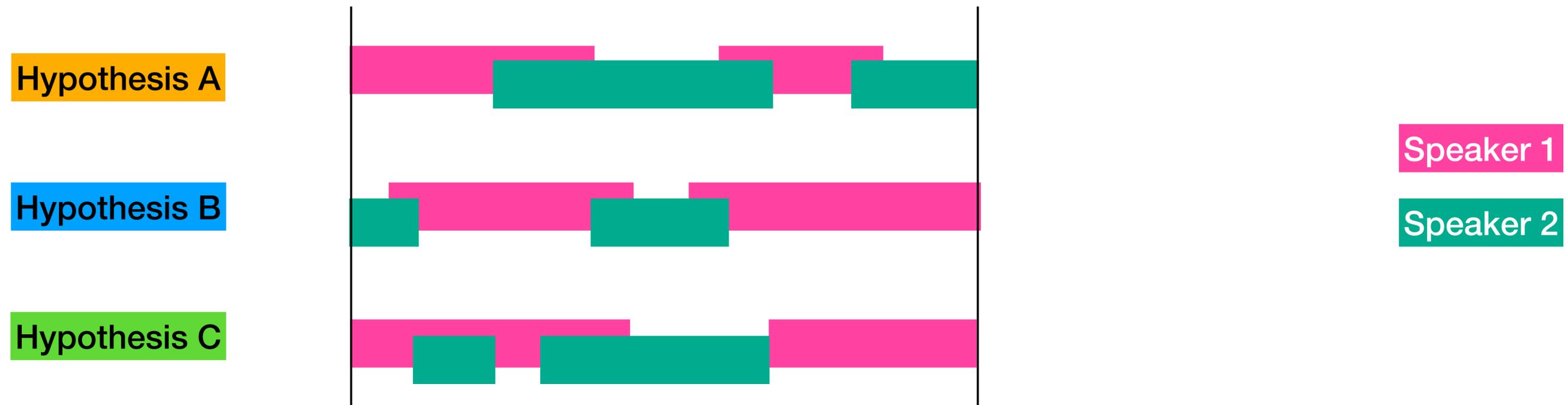


Hypothesis C



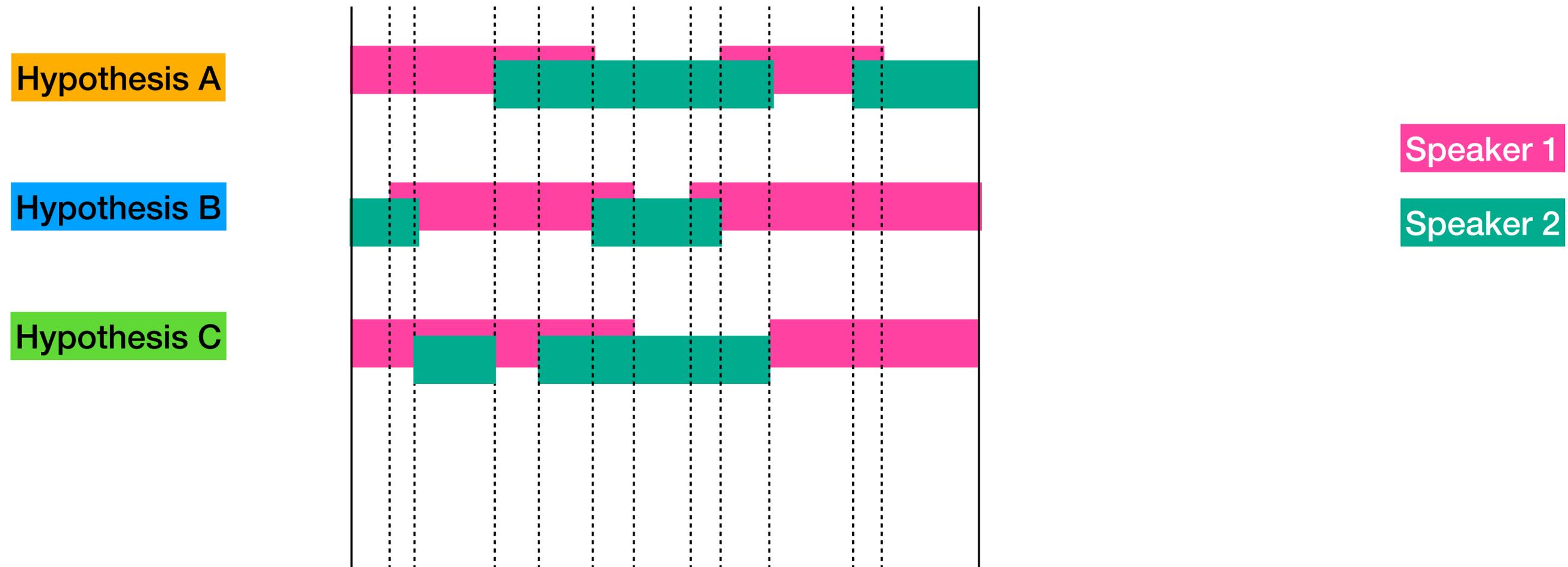
DOVER-Lap label voting

Consider 3 hypotheses from overlap-aware diarization systems



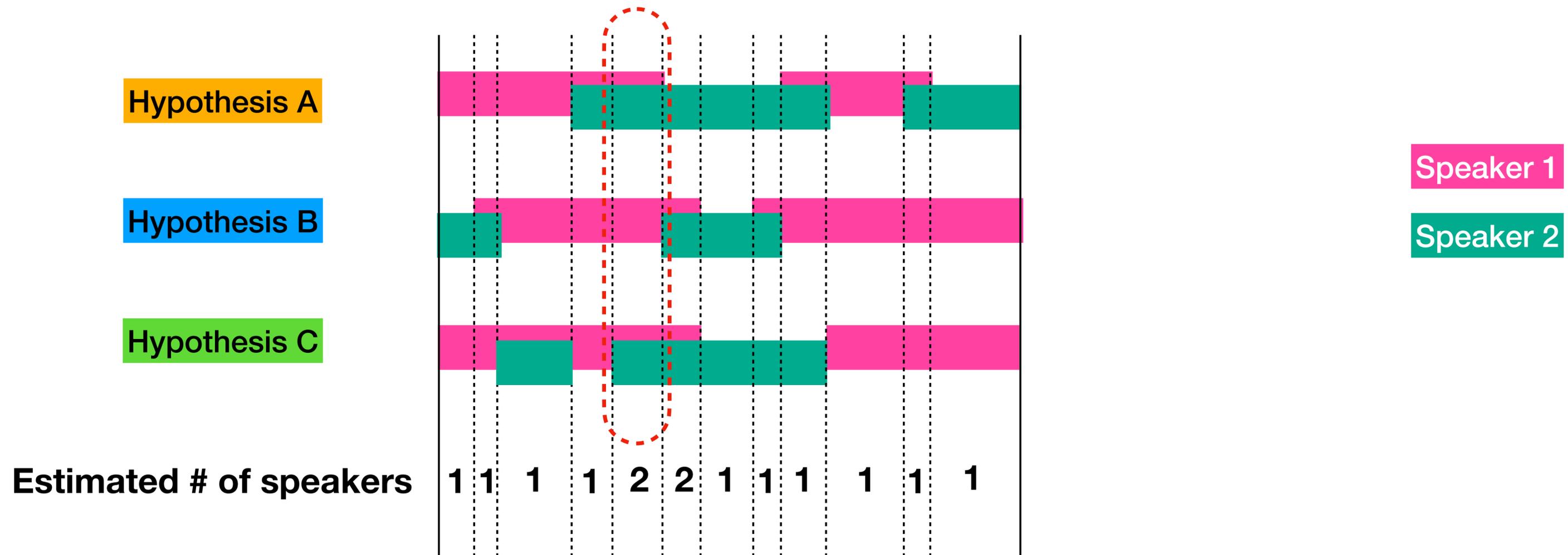
DOVER-Lap label voting

Divide into regions (similar to DOVER)



DOVER-Lap label voting

Estimate number of speakers in each region

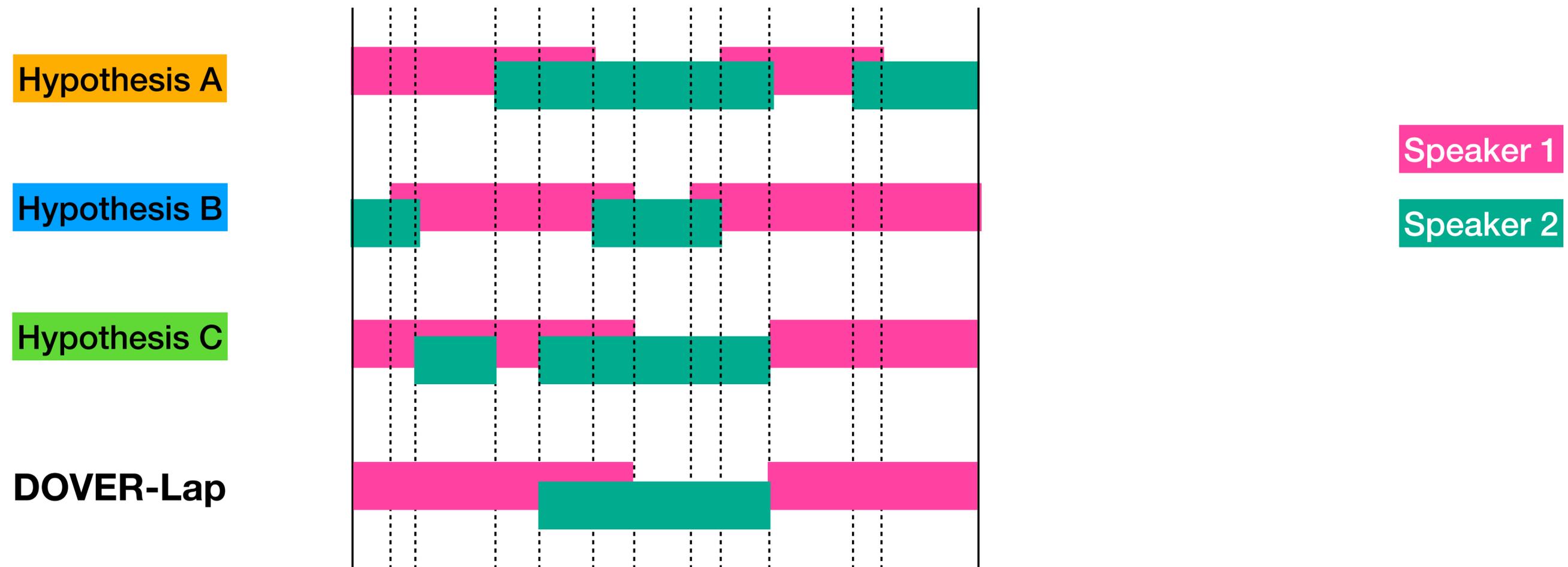


speakers = weighted mean of # speakers in hypotheses

Weights -> obtained by ranking hypotheses by **total cost**

DOVER-Lap label voting

Assign highest weighted N speakers in each region



DOVER-Lap results: AMI

Effect of global label mapping algorithm

System	Spk. conf.	DER
Overlap-aware SC	10.1	23.6
VB-based overlap assignment*	9.6	21.5
Region proposal network	8.3	25.5
Average	9.3	23.5
DOVER	10.6	30.5
+ global label mapping	5.1	25.0

AMI data contains **4-speaker meetings**

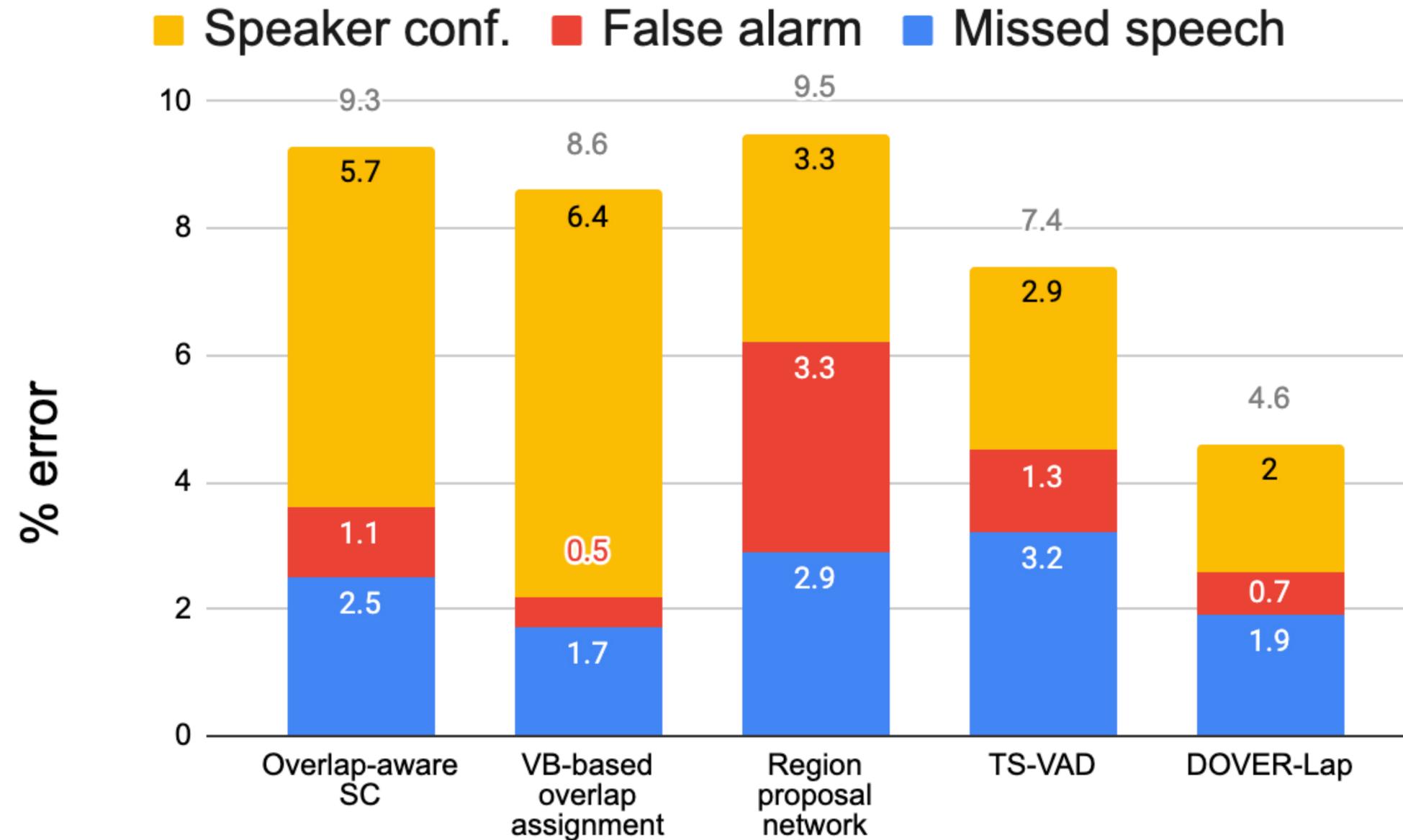
DOVER-Lap results: AMI

Effect of rank-weighted majority voting

System	Spk. conf.	DER
Overlap-aware SC	10.1	23.6
VB-based overlap assignment*	9.6	21.5
Region proposal network	8.3	25.5
Average	9.3	23.5
DOVER	10.6	30.5
+ global label mapping	5.1	25.0
DOVER-Lap	7.6	20.3

Results: Breakdown on LibriCSS

Effectively combines complementary strengths

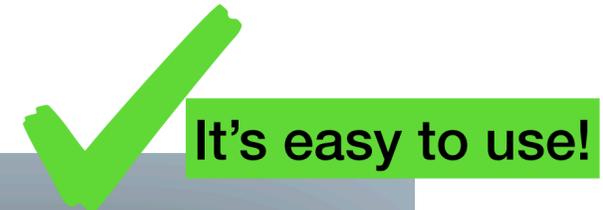


Results from DIHARD-3

Top 2 teams used DOVER-Lap for system fusion in DIHARD-3

#1: USTC team combined clustering, separation-based, and TS-VAD systems

#2: Hitachi-JHU team combined VB-based and EEND-based systems



```
$ pip install dover-lap
```

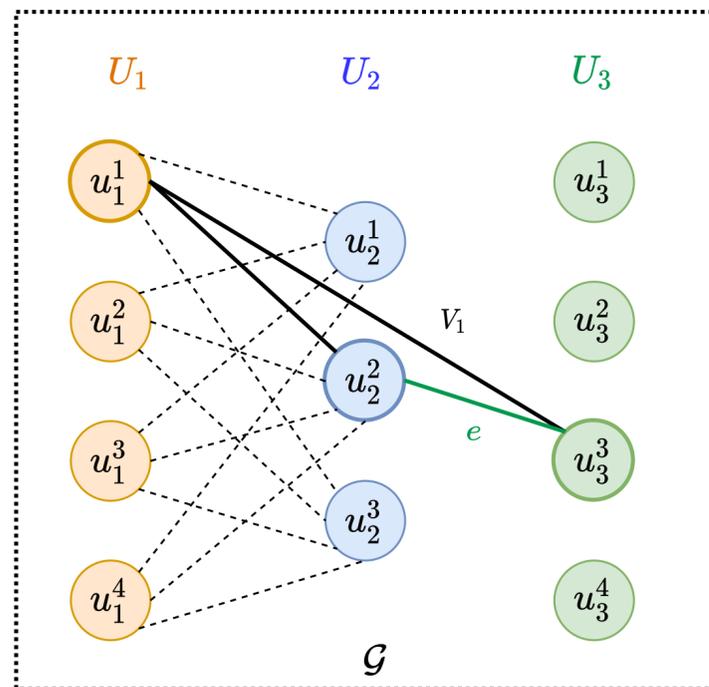
```
$ dover-lap <output-rttm> <input-rttms>
```

Wang, Y., et al. USTC-NELSLIP System Description for DIHARD-III Challenge. ArXiv, abs/2103.10661.

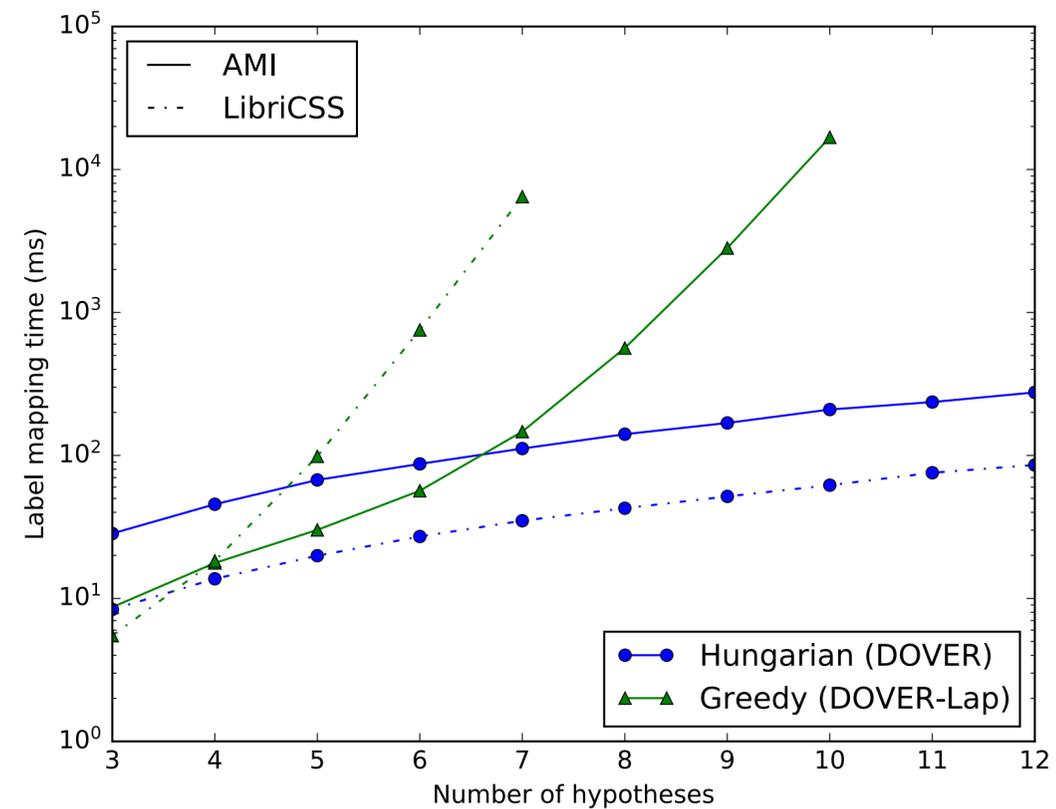
Horiguchi, S., et al. The Hitachi-JHU DIHARD III System: Competitive End-to-End Neural Diarization and X-Vector Clustering Systems Combined by DOVER-Lap. ArXiv, abs/2102.01363.

New analysis

Label mapping is a graph partitioning problem,
DOVER-Lap algorithm is exponential!



$$w(e) = \frac{\Delta(u_2^2) \cap \Delta(u_3^3)}{\Delta(u_2^2) \cup \Delta(u_3^3)}$$



Raj, D., & Khudanpur, S. (2021). Reformulating DOVER-Lap Label Mapping as a Graph Partitioning Problem. ArXiv, abs/2104.01954.

New analysis

Modified Hungarian algorithm is fast and accurate

System	Spk. conf.	DER
Agglomerative Hierarchical	10.1	23.6
VB-based overlap assignment*	9.6	21.5
Region proposal network	8.3	25.5
Average	9.3	23.5
DOVER-Lap	7.6	20.3
Hungarian (modified)	8.2	20.9

Raj, D., & Khudanpur, S. (2021). Reformulating DOVER-Lap Label Mapping as a Graph Partitioning Problem. ArXiv, abs/2104.01954.

A word on evaluation

<https://github.com/desh2608/spyder>

- 4-5x faster than [md-eval.pl](https://github.com/desh2608/md-eval.pl) and dscore
- Use from Python or as CLI tool
- Selectively evaluate on single-speaker or overlapping regions
- Other metrics (JER) coming soon...

```
import spyder

# reference (ground truth)
ref = [("A", 0.0, 2.0), # (speaker, start, end)
       ("B", 1.5, 3.5),
       ("A", 4.0, 5.1)]

# hypothesis (diarization result from your algorithm)
hyp = [("1", 0.0, 0.8),
       ("2", 0.6, 2.3),
       ("3", 2.1, 3.9),
       ("1", 3.8, 5.2)]

metrics = spyder.DER(ref, hyp)
print(metrics)
# DERMetrics(duration=5.10,miss=9.80%,falarm=21.57%,conf=25.49%,der=56.86%)
```

Summary

Diarization is a useful but difficult task.

Clustering-based systems fall short on handling overlapping speech, but small modifications inspired from mathematical insights can change this.

Continuous Speech Separation (CSS) works well with clustering-based systems, but well-trained separation module is required.

Ensembles work. Use **DOVER-Lap** for your challenge submissions.

Collaborators

Overlap-aware spectral clustering: Zili Huang, Sanjeev Khudanpur

CSS-based diarization: Zhuo Chen, Hakan Erdogan, Maokui He, Zili Huang, Shinji Watanabe

DOVER-Lap: Paola Garcia, Zili Huang, Shinji Watanabe, Dan Povey, Andreas Stolcke, Sanjeev Khudanpur

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Special thanks to:

Takuya Yoshioka (Microsoft), for providing data simulation scripts.

Shota Horiguchi (Hitachi) for suggesting a modification for DOVER-Lap.